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Cosmological Shapes of Higher-Spin Gravity

D. Anninos,^a V. De Luca,^b G. Franciolini,^b A. Kehagias,^c A. Riotto^b

^aDepartment of Mathematics, King's College London, Strand, London WC2R 2LS, UK

^bDepartment of Theoretical Physics and Center for Astroparticle Physics (CAP)

24 quai E. Ansermet, CH-1211 Geneva 4, Switzerland

^cPhysics Division, National Technical University of Athens 15780 Zografou Campus, Athens, Greece

E-mail: dionysios.anninos@kcl.ac.uk, valerio.deluca@unige.ch,
gabriele.franciolini@unige.ch, kehagias@central.ntua.gr, antonio.riotto@unige.ch

Abstract. We explore non-Gaussian features of a massless spin-two field in the Vasiliev theory of higher-spin gravity. The theory contains an infinite tower of interacting gauge fields with increasing spin, and admits four-dimensional asymptotically de Sitter configurations. Using a recent proposal for calculating late-time quantum correlations in Vasiliev theory, we provide an exact formula for the tensor non-Gaussianities of the massless spin-two graviton field. By general symmetry considerations, we relate our result to that produced by a tree-level calculation in a gravitational theory containing an Einstein term and a term cubic in the Weyl tensor. The relative coefficient between the two terms is calculated explicitly, exhibiting a significant contribution from the Weyl cubed term. We discuss potential cosmological implications of our results.

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1 Introduction

Higher-spin theories are field theories containing an infinite tower of interacting gauge fields with increasing spin. Their spectrum includes a massless spin-two field. In Minkowski space, one can devise no-go theorems [1–3] which render the S-matrix of a theory with higher-spin conserved charges essentially trivial. These no-go theorems can be avoided if the spacetime is no longer asymptotically flat [4]. Indeed, non-linear classical equations of motion for interacting massless higher-spin fields in a curved background were obtained by Vasiliev [5–7]. Here, we consider those Vasiliev theories which admit a four-dimensional de Sitter solution [8, 9].

That Vasiliev’s higher-spin theory admits asymptotically de Sitter configurations may be of interest for cosmology. There are important observational indications that our universe underwent a period of accelerated expansion – the primordial inflationary era – at an early stage. During this period, the universe is described by an approximately de Sitter spacetime (for a review see [10]). Consequently, we are prompted to ask whether the inflationary era could be of the higher-spin type, and if so, what would the observational imprints for such a scenario be [11–13].

In this paper we take a few steps toward addressing this question. Concretely, we calculate and analyse the exact three-point cosmological correlator of the higher-spin graviton in the minimal Vasiliev theory whose spectrum comprises a particle for every even spin.¹ In order to analyse the graviton non-Gaussianities, we use the framework of [26] which we occasionally refer to as the Q -formalism. The Q -formalism circumvents the formidable task of calculating quantities in the original Vasiliev formalism [27] by exploiting the description of higher-spin gravity theory in terms of a vector-like conformally invariant theory. The basic proposal of [26] is that the microscopic operator content of the higher-spin theory is given by $2N$ local Hermitian operators $\hat{Q}^\alpha(\vec{x})$, and other $2N$ local Hermitian operators $\hat{\Pi}^\alpha(\vec{x})$ satisfying a non-trivial operator algebra. Higher-spin fields are identified with specific composite operators built from the \hat{Q} and $\hat{\Pi}$. One further identifies a particular quantum state in the Hilbert space acted on by the \hat{Q} and $\hat{\Pi}$ with the de Sitter invariant Bunch-Davies state, which turns out to be a Gaussian functional in Q . In doing so, the Q -formalism provides a systematic framework to extract exact expressions for late-time cosmological correlation functions. The results obtained through the Q -formalism agree with all previously known tree-level calculations [28–31]. Moreover, the correlators calculated by the Q -formalism encode non-linear effects of the higher-spin theory, such as those produced by the exchange of an infinite tower of massless higher-spin fields. Though not analysed in this paper, it is of much interest to assess the locality properties and ultraviolet features of Vasiliev theory (along the lines of [24]) using the correlation functions obtained through the Q -formalism.

Our results are nicely complemented by a general symmetry argument. It was shown in [32] that the de Sitter isometries fix, perturbatively, the possible shapes of the three-point graviton correlators to two possible structures. These can be obtained from a tree-level calculation in the following theory

$$S_g = \frac{M_p^2}{2} \int d^4x \sqrt{-g} (R - 6H^2) + \frac{M_p^2 L^4}{2} \int d^4x \sqrt{-g} W^{\mu\nu}{}_{\rho\sigma} W^{\rho\sigma}{}_{\delta\tau} W^{\delta\tau}{}_{\mu\nu} . \quad (1.1)$$

Here M_p is the Planck mass, H is the Hubble scale, $W_{\mu\nu\rho\sigma}$ is the Weyl tensor, and L is a parameter with dimension of length. Our dimensionless parameter N is of the order M_p^2/H^2 , which current data set to be at least of the order of 10^9 . The contribution due to the Einstein term has been computed in [33]. The same three-point structures can be obtained from considerations of three-dimensional conformal field theory [34, 35]. There, the stress energy-momentum tensor is

¹For inflationary signatures of massive or partially massless higher-spin fields, see [13–25].

constrained by conformal symmetries to be a linear combination of two structures (in the absence of parity violating terms): the stress tensor three-point functions from free scalar and free fermion theories. One way to think about the scale L in the context of inflation, is as an additional scale on top of the Planck and Hubble scales. Imagine, for instance, that L is the string length in a weakly coupled string theory with $1 \ll LM_{\text{p}}$. When the higher-spin string states are very massive with respect to H we have $1 \gg HL \gg H/M_{\text{p}}$. In another regime, where $1 \ll M_{\text{p}}/H$ and $HL \lesssim 1$, the string states are light with respect to the Hubble scale during inflation (without losing perturbative control of the string). In this second scenario, we should consider a tower of light higher-spin particles in an approximate de Sitter background. In the absence of experimental data on the number HL , such a scenario seems phenomenologically viable. We will calculate HL exactly for the Vasiliev theory to confirm that it falls under the second category. In other words, the higher-spin theory under consideration generates a different graviton three-point from that of Einstein gravity [36]. The difference can be viewed as originating from a cubic Weyl term with a specific coefficient.

That the early phase of the universe may be of the higher-spin type is an appealing scenario. However, we are still left with the important and open problem of describing the exit from inflation, as well as the generation of scalar fluctuations with the observed scalar tilt. We do not resolve these issues, although we briefly offer some speculative remarks in the conclusions.

The paper is organised as follows. In section 2 we briefly review aspects of the Q -formalism. Section 3 contains the calculation of the two-point correlator of the spin-2 field. Section 4 is devoted to the calculation of the three-point function of the spin-2 field. Section 5 relates the three-point function to that stemming from an Einstein plus cubic Weyl term, and we provide the specific value of HL . In section 6 we discuss the shape of the tensor non-Gaussianities. Finally, in section 7 we offer some concluding remarks. The paper contains several appendices where technical details for the calculations can be found.

2 Review of the Q -formalism

In this section we briefly summarise the proposal put forward in Ref. [26]. The reader is invited to read this reference for more details.

2.1 The free massless spin- s in de Sitter spacetime

Let us consider a de Sitter spacetime with conformal time η and metric

$$ds^2 = \frac{1}{H^2\eta^2} (-d\eta^2 + d\vec{x}^2) \ , \quad \vec{x} \in \mathbb{R}^3 \ , \quad \eta \in (-\infty, 0) \ . \quad (2.1)$$

A free massless field of integer spin- s is described a totally symmetric tensor $\phi_{\mu_1 \dots \mu_s}(\eta, \vec{x})$ obeying the free Fronsdal equation [37, 38]. Due to the gauge symmetry, the field is invariant under the following transformation

$$\delta\phi_{\mu_1 \dots \mu_s} = \nabla_{(\mu_1} \Lambda_{\mu_2 \dots \mu_s)} \ , \quad (2.2)$$

with an arbitrary traceless gauge parameter,

$$\Lambda^\nu_{\nu\mu_3 \dots \mu_{s-1}} = 0. \quad (2.3)$$

Moreover, for $s \geq 4$ the fields obey the double-traceless condition $\phi^{\alpha\beta}_{\alpha\beta\mu_1 \dots \mu_{s-4}} = 0$. The gauge invariance implies that each higher-spin field contains only two physical degrees of freedom, since

one can use it to set its redundant components to zero. The mode expansion of the $\phi_{i_1 \dots i_s}(\eta, \vec{x})$ reads²

$$\phi_{i_1 \dots i_s}(\eta, \vec{x}) = \sqrt{\gamma} \sum_{\lambda} \int_k \left(a_k^{\lambda} \psi_{k, i_1 \dots i_s}^{\lambda}(\eta) e^{i\vec{k} \cdot \vec{x}} + \text{h.c.} \right). \quad (2.4)$$

Here, $\delta^{i_1 i_2} \psi_{k, i_1 i_2 \dots i_s}^{\lambda} = k^{i_1} \psi_{k, i_1 \dots i_s}^{\lambda} = 0$, and λ indicates the helicity. The creation and annihilation operators satisfy the canonical commutation relations

$$[a_{\vec{k}}^{\lambda}, a_{\vec{k}'}^{\lambda' \dagger}] = \delta^{\lambda \lambda'} \delta_{\vec{k} + \vec{k}'}. \quad (2.5)$$

The parameter γ is a normalisation factor which accounts for the fact that in the action the coefficient of the kinetic term of the field might not be $1/2$, but rather $1/2\gamma$. The vacuum two-point function in momentum space is

$$\langle 0 | \phi_{i_1 \dots i_s}(\eta, \vec{k}) \phi_{i'_1 \dots i'_s}(\eta', \vec{k}') | 0 \rangle = \gamma(\eta\eta')^{\frac{3}{2}-s} \frac{\pi}{4} H_{s-\frac{1}{2}}^{(1)}(-k\eta) H_{s-\frac{1}{2}}^{(2)}(-k\eta') \Pi_{i_1 \dots i_s, i'_1 \dots i'_s}(\vec{k}) \delta_{\vec{k} + \vec{k}'}. \quad (2.6)$$

Here $\Pi_{i_1 \dots i_s, i'_1 \dots i'_s}(\vec{k})$ indicates the projector onto spin- s transverse traceless polarisations (see Appendix A for more details),

$$\Pi_{i_1 \dots i_s, i'_1 \dots i'_s}(\vec{k}) = \sum_{\lambda} \epsilon_{i_1 \dots i_s}^{\lambda}(\vec{k}) \epsilon_{i'_1 \dots i'_s}^{*\lambda}(\vec{k}), \quad (2.7)$$

and we have introduced the polarisation tensors $\epsilon_{i_1 \dots i_s}^{\lambda}(\vec{k})$ satisfying the following rule³

$$\sum_{i_1 \dots i_s} \epsilon_{i_1 \dots i_s}^{*\lambda_1} \epsilon_{i_1 \dots i_s}^{\lambda_2} = \delta^{\lambda_1 \lambda_2}. \quad (2.8)$$

If we decompose the Hankel functions of the first kind as $H_{\nu}^{(1)}(z) = J_{\nu}(z) + iY_{\nu}(z)$, we can rewrite the expression for the modes as

$$\phi_{i_1 \dots i_s}(\eta, \vec{x}) = (-\eta) \int_k \left(\alpha_{i_1 \dots i_s}(\vec{k}) \bar{J}_{s-\frac{1}{2}}(-k\eta) + \tilde{\beta}_{i_1 \dots i_s}(\vec{k}) \bar{Y}_{s-\frac{1}{2}}(-k\eta) \right) e^{i\vec{k} \cdot \vec{x}}, \quad (2.9)$$

with

$$\bar{J}_{\nu}(z) \equiv \sqrt{\frac{\pi}{2}} z^{-\nu} J_{\nu}(z), \quad \bar{Y}_{\nu}(z) \equiv \sqrt{\frac{\pi}{2}} z^{-\nu} Y_{\nu}(z), \quad (2.10)$$

and

$$\alpha_{i_1 \dots i_s}(\vec{k}) = \sqrt{\gamma} k^{s-\frac{1}{2}} (a_{\vec{k}}^{\lambda} \epsilon_{i_1 \dots i_s}^{\lambda} + a_{\vec{k}}^{\dagger \lambda} \epsilon_{i_1 \dots i_s}^{*\lambda}) / \sqrt{2}, \quad (2.11)$$

$$\tilde{\beta}_{i_1 \dots i_s}(\vec{k}) = \sqrt{\gamma} k^{s-\frac{1}{2}} i (a_{\vec{k}}^{\lambda} \epsilon_{i_1 \dots i_s}^{\lambda} - a_{\vec{k}}^{\dagger \lambda} \epsilon_{i_1 \dots i_s}^{*\lambda}) / \sqrt{2}. \quad (2.12)$$

The fields $\alpha_{i_1 \dots i_s}(\vec{k})$ and $\tilde{\beta}_{i_1 \dots i_s}(\vec{k})$ have conformal dimension $\tilde{\Delta} = s + 1$. If we expand at late times (i.e. $\eta \rightarrow 0$) we arrive at⁴

$$\phi_{i_1 \dots i_s}(\eta, \vec{x}) \approx \int_k \left(c_1 \alpha_{i_1 \dots i_s}(\vec{k}) \eta + c_2 k^{1-2s} \tilde{\beta}_{i_1 \dots i_s}(\vec{k}) \eta^{2-2s} \right) e^{i\vec{k} \cdot \vec{x}}, \quad (2.13)$$

²From now on we will use the following shorthand notations of Ref. [26]

$$\int_k = \int \frac{d^3 k}{(2\pi)^3}, \quad \delta_{\vec{k} + \vec{k}'} = (2\pi)^3 \delta^{(3)}(\vec{k} + \vec{k}').$$

³We leave the basis choice free for the moment. In the following we will specialise our results using both the basis X and P adopted in Ref. [32] (where the polarisation tensors are real) and the chiral basis.

⁴Note that the spin-2 graviton is identified here as the perturbation of the metric as $ds^2 = (-d\eta^2 + d\vec{x}^2) / H^2 \eta^2 + h_{ij}(\eta, \vec{x}) dx^i dx^j / H^2$. In the following we will use the more standard cosmology notation and identify the graviton with the perturbation of the spatial part of the metric as $\gamma_{ij}(\eta, \vec{x}) dx^i dx^j / H^2 \eta^2$.

with $c_1 = -\sqrt{\pi/2}(1/2^\nu \Gamma(\nu + 1))$ and $c_2 = -\sqrt{\pi/2} 2^\nu \Gamma(\nu)/\pi$, $\nu = s - 1/2$. One can define a boundary field $\beta(\vec{x})$ related to $\tilde{\beta}(\vec{x})$ by the following transformation in momentum space

$$\tilde{\beta}_{i_1 \dots i_s}(\vec{k}) = k^{2s-1} \beta_{i_1 \dots i_s}(\vec{k}) = \int_{\vec{k}'} G_{i_1 \dots i_s, i'_1 \dots i'_s}(\vec{k}, \vec{k}') \beta_{i'_1 \dots i'_s}(\vec{k}'), \quad (2.14)$$

where

$$G_{i_1 \dots i_s, i'_1 \dots i'_s}(\vec{k}, \vec{k}') = k^{2s-1} \Pi_{i_1 \dots i_s, i'_1 \dots i'_s}(\vec{k}) \delta_{\vec{k}+\vec{k}'}. \quad (2.15)$$

Since $G_{i_1 \dots i_s, i'_1 \dots i'_s}$ represents the two-point function of a spin- s conserved current, this can be interpreted as the CFT shadow transform, which we discuss in Appendix B. As a consequence, the field $\beta(\vec{x})$ transforms as a spin- s primary field with conformal dimension $\Delta = 2 - s$, while $\tilde{\beta}(\vec{x})$ transforms as a spin- s primary field of conformal dimension $\tilde{\Delta} = s + 1$, with $\Delta + \tilde{\Delta} = 3$.

2.2 Microscopic operator content

In Ref. [26] it was argued that the microscopic operator content of the theory is given by $2N$ Hermitian operators $\hat{Q}^\alpha(\vec{x})$, and other additional $2N$ Hermitian operators $\hat{\Pi}^\alpha(\vec{x})$, with $\alpha = 1, \dots, 2N$. In the semi-classical regime the dimensionless parameter N , which goes as M_p^2/H^2 , is very large. The microscopic operators satisfy the algebra

$$[\hat{Q}^\alpha(\vec{x}), \hat{\Pi}^\beta(\vec{y})] = i\delta(\vec{x} - \vec{y})\delta^{\alpha\beta}, \quad (2.16)$$

with all other commutators vanishing. From now on, we will work in the \hat{Q} -eigenbasis, in which we can identify the late-time Bunch-Davies quantum state with the Gaussian wavefunctional:

$$\Psi(Q) = \exp \left[\frac{1}{2} \int_x Q^\alpha(\vec{x}) \partial_x^2 Q^\alpha(\vec{x}) \right]. \quad (2.17)$$

The integration measure for the Q is the standard flat measure. The Gaussian structure of Ψ allows us to calculate all expectation values using relatively simple Wick contractions.

The higher-spin boundary fields $\tilde{\beta}_{i_1 \dots i_s}(\vec{x})$ are identified with the bilinear operators

$$B_{s, i_1 \dots i_s}(\vec{x}) = \frac{1}{N} \int d^3y : Q^\alpha(\vec{x}) \mathcal{D}_{i_1 \dots i_s}(\vec{x}, \vec{y}) Q^\alpha(\vec{y}) : , \quad (2.18)$$

where the differential operator $\mathcal{D}_{i_1 \dots i_s}$ are those appearing in the construction of conserved currents in the free $O(2N)$ model. The positive integer N is proportional to the square of the ratio between the Planck mass and the Hubble rate. The symbol $: :$ represents normal ordering. It will be convenient to introduce the shadow transform $\mathcal{B}_{s, i'_1 \dots i'_s}$ of the bilinear $B_{s, i_1 \dots i_s}$

$$B_{s, i_1 \dots i_s}(\vec{k}) = \int_{\vec{k}'} G_{i_1 \dots i_s, i'_1 \dots i'_s}(\vec{k}, \vec{k}') \mathcal{B}_{s, i'_1 \dots i'_s}(\vec{k}'), \quad (2.19)$$

It then follows that one can identify the boundary higher-spin profiles $\beta_{i_1 \dots i_s}$ with the bilinears $\mathcal{B}_{s, i_1 \dots i_s}$. In Fig. 1 we show a schematic representation of the various relations.

In order to efficiently generate the higher-spin currents constructed out from the $2N$ bosonic real fields $Q^\alpha(\vec{x})$, one makes use of the equivalence between traceless symmetric tensors and functions of a complex null vector z to build up the scalar

$$B_s(\vec{x}|z) \equiv B_{s, i_1 \dots i_s}(\vec{x}) z^{i_1} \dots z^{i_s} \propto \sum_{k=0}^s a_k^{(s)} (z \cdot \partial)^k Q^\alpha(\vec{x}) (z \cdot \partial)^{s-k} Q^\alpha(\vec{x}), \quad (2.20)$$

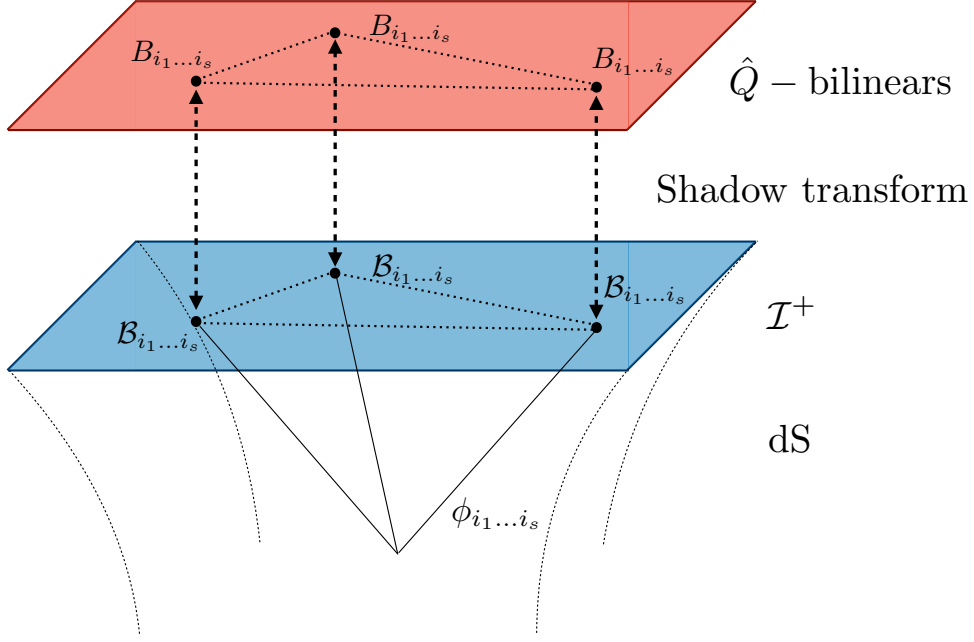


Figure 1. Pictorial representation of the identification between bulk effective fields and the microscopic bilinear operators. \mathcal{I}^+ denotes the future boundary of de Sitter space.

which should be restricted to the submanifold $z^2 = 0$. The coefficients a_k of the expansion are defined by the rule

$$\sum_{k=0}^s a_k^{(s)} x^k y^{s-k} = f_s(x, y), \quad (2.21)$$

where one chooses

$$f_s(x, y) = \frac{2^{(5-s)/2}}{N} (x+y)^s T_s\left(\frac{x-y}{x+y}\right) \quad (2.22)$$

in order to normalise properly the two-point functions. Here $T_s(u)$ represents the Chebyshev polynomial of order s .

As an example, the spin-2 field $B_2(\vec{x}|z)$ can be written as [26, 39]

$$B_2(\vec{x}|z) = \frac{2\sqrt{2}}{N} : [(z \cdot \partial)^2 Q^\alpha(\vec{x}) Q^\alpha(\vec{x}) + Q^\alpha(\vec{x}) (z \cdot \partial)^2 Q^\alpha(\vec{x}) - 6(z \cdot \partial) Q^\alpha(\vec{x}) (z \cdot \partial) Q^\alpha(\vec{x})] : . \quad (2.23)$$

In general, the correlator of two higher-spin fields B_s with these normalisations becomes

$$\langle B_s(\vec{x}_1|z_1) B_{s'}(\vec{x}_2|z_2) \rangle = \frac{(2s)!}{\pi^2 N} \frac{(z_1 \cdot H(x_{12}) \cdot z_2)^s}{(x_{12}^2)^{1+s}} \delta_{ss'} , \quad (2.24)$$

valid for $s \geq 1$. Here $H_{ij}(x) = \delta_{ij} - 2x_i x_j / x^2$ and $x_{ij} = \vec{x}_i - \vec{x}_j$. For scalar and spin-2 operators, the two-point functions are of the form

$$\langle B_0(\vec{x}_1) B_0(\vec{x}_2) \rangle = \frac{1}{N} \frac{1}{2\pi^2 x_{12}^2}, \quad \langle B_2(\vec{x}_1|z_1) B_2(\vec{x}_2|z_2) \rangle = \frac{1}{N} \frac{4!(z_1 \cdot H(x_{12}) \cdot z_2)^2}{\pi^2 x_{12}^6} . \quad (2.25)$$

The equation above also fixes the normalisation coefficient γ to be $2/N$. In momentum space, the polynomials are Fourier transformed and, for example, spin-zero and spin-2 fields take the

following expression

$$B_0(p) = \frac{2\sqrt{2}}{N} \int_q :Q_q^\alpha Q_{p-q}^\alpha:, \quad (2.26)$$

$$B_2(p|z) = -\frac{2\sqrt{2}}{N} \int_q :Q_q^\alpha Q_{p-q}^\alpha: [(z \cdot q)^2 + (z \cdot (p - q))^2 + 6(z \cdot q)z \cdot (q - p)]. \quad (2.27)$$

One can go back and find the original tensors correlator by factorising and dropping the z vectors. For example, the graviton three-point function can be written as

$$\langle B_2(p_1|z_1)B_2(p_2|z_2)B_2(p_3|z_3) \rangle = \langle B_{2,ab}(p_1)B_{2,ij}(p_2)B_{2,mn}(p_3) \rangle z_1^a z_1^b z_2^i z_2^j z_3^m z_3^n. \quad (2.28)$$

Once these boundary correlators have been calculated, one has to apply the shadow transform explained in Appendix B.

2.3 Relation to dS/CFT

In the context of higher-spin gravity, the Q -formalism can be viewed as a completion of the proposal [33] that the late-time de Sitter invariant Euclidean wavefunctional ψ_0 [40–47] is calculated by a CFT partition function. At the semi-classical level, ψ_0 is a functional of the late-time profiles $\beta_{i_1 \dots i_s}(\vec{x})$ of all the higher-spin fields. From the dual CFT perspective, the $\beta_{i_1 \dots i_s}(\vec{x})$ are understood as sources for each conserved current operator [28]. In order to calculate actual expectation values, we must integrate $|\psi_0|^2$ over all these profiles using an integration measure invariant under all the higher-spin gauge symmetries. In the semi-classical limit, and at low enough order in perturbation theory, this measure can be taken to be flat. More generally, however, the assumption of a flat measure need not hold. The original dS/CFT proposal does not provide an integration measure. In calculating physical expectation values of bulk fields, the Q -formalism implicitly provides an exact integration measure, thus completing the original dS/CFT proposal. Wherever a direct comparison is available, such as the semi-classical or perturbative limit, the two proposals are in complete agreement. Moreover, the Q -formalism extends the dS/CFT story by providing a complete Hilbert space and microscopic operator content for the bulk theory, as opposed to the description of a single quantum state.

3 Two-point correlator of the spin-2 field

We are now ready to compute the graviton correlators. In this section we consider the two-point function in momentum space. We present it since it is simpler than the calculation of the three-point correlator and we can highlight some of the technical details involved. These will be useful when dealing with the more involved calculation of the three-point correlator.

3.1 Real space

One straightforward way to get the two-point correlator of the spin-2 field is to start from its expression in position space, given by Eq. (2.24)

$$\langle B_2(\vec{x}_1|z_1)B_2(\vec{x}_2|z_2) \rangle = \frac{1}{N} \frac{4!(z_1 \cdot H(x_{12}) \cdot z_2)^2}{\pi^2 x_{12}^6}. \quad (3.1)$$

Performing the Fourier transformation to express the expectation value in momentum space and picking up the null vectors z_1 and z_2 , we obtain

$$\langle B_{2,ij}(p_1)B_{2,lm}(p_2) \rangle = \frac{1}{N} p_1^3 \Pi_{ij,lm}(p_1) \delta_{\vec{p}_1 + \vec{p}_2}. \quad (3.2)$$

We can now apply the shadow transform to obtain the local boundary fields as shown in Eq. (B.6) to get

$$\langle \mathcal{B}_{2,ij}(p_1) \mathcal{B}_{2,lm}(p_2) \rangle = \frac{1}{p_1^3 p_2^3} \Pi^{i'j'}_{,ij}(\vec{p}_1) \Pi^{l'm'}_{,lm}(\vec{p}_2) \langle B_{2,i'j'}(p_1) B_{2,l'm'}(p_2) \rangle = \frac{1}{N} \frac{1}{p_1^3} \Pi_{ij,lm}(\vec{p}_1) \delta_{\vec{p}_1 + \vec{p}_2}. \quad (3.3)$$

This equation provides the expression for the two-point function of the spin-2 field in momentum space. We now turn to the computation of the same expectation value through the formalism outlined in the previous section.

3.2 Momentum space

The two-point function of the spin-2 field can be obtained starting from the expression of the spin-2 field in Eq. (2.26)

$$\begin{aligned} \langle B_2(p_1|z_1) B_2(p_2|z_2) \rangle &= \frac{8}{N^2} \int_{k_1} \int_{k_2} \langle :Q_{k_1} Q_{p_1-k_1} : : Q_{k_2} Q_{p_2-k_2} : \rangle \\ &\quad \times [(z_1 \cdot k_1)^2 + (z_1 \cdot (p_1 - k_1))^2 + 6(z_1 \cdot k_1) z_1 \cdot (k_1 - p_1)] \\ &\quad \times [(z_2 \cdot k_2)^2 + (z_2 \cdot (p_2 - k_2))^2 + 6(z_2 \cdot k_2) z_2 \cdot (k_2 - p_2)]. \end{aligned} \quad (3.4)$$

We explicitly compute the normal ordered expectation value as

$$\langle :Q_{k_1} Q_{p_1-k_1} : : Q_{k_2} Q_{p_2-k_2} : \rangle = N k_1^{-2} k_2^{-2} \delta_{\vec{k}_1 + \vec{p}_2 - \vec{k}_2} \delta_{\vec{k}_2 + \vec{p}_1 - \vec{k}_1}. \quad (3.5)$$

Thus,

$$\begin{aligned} \langle B_2(p_1|z_1) B_2(p_2|z_2) \rangle &= \frac{8}{N} \int_{k_1} \int_{k_2} k_1^{-2} k_2^{-2} \delta_{\vec{p}_1 - \vec{k}_1 + \vec{k}_2} \delta_{\vec{p}_2 - \vec{k}_2 + \vec{k}_1} \\ &\quad \times [(z_1 \cdot k_1)^2 + (z_1 \cdot (p_1 - k_1))^2 + 6(z_1 \cdot k_1) z_1 \cdot (k_1 - p_1)] \\ &\quad \times [(z_2 \cdot k_2)^2 + (z_2 \cdot (p_2 - k_2))^2 + 6(z_2 \cdot k_2) z_2 \cdot (k_2 - p_2)]. \end{aligned} \quad (3.6)$$

The result depends on a minimal set of integrals as follows

$$\begin{aligned} \langle B_2(p_1|z_1) B_2(p_2|z_2) \rangle &= \frac{8}{N} \delta_{\vec{p}_1 + \vec{p}_2} (A_{z_1, z_2} + B_{z_1, z_2} + C_{z_1, z_2} + C_{z_2, z_1} \\ &\quad + 6D_{z_1, z_2} + 6D_{z_2, z_1} + 6E_{z_1, z_2} + 6E_{z_2, z_1} + 36F_{z_1, z_2}), \end{aligned} \quad (3.7)$$

where we have defined

$$\begin{aligned} A_{z_1, z_2} &= z_{1i} z_{1j} z_{2l} z_{2m} \int_{k_1} \frac{1}{|\vec{k}_1|^2} \frac{1}{|\vec{k}_1 - \vec{p}_1|^2} \left(k_1^i k_1^j k_1^l k_1^m \right) \equiv z_{1i} z_{1j} z_{2l} z_{2m} I_A^{ijlm}, \\ B_{z_1, z_2} &= z_{1i} z_{1j} z_{2l} z_{2m} \int_{k_1} \frac{1}{|\vec{k}_1|^2} \frac{1}{|\vec{k}_1 - \vec{p}_1|^2} [(k_1 - p_1)^i (k_1 - p_1)^j (k_1 - p_1)^l (k_1 - p_1)^m] \\ &\quad \equiv z_{1i} z_{1j} z_{2l} z_{2m} I_B^{ijlm}, \\ C_{z_1, z_2} &= z_{1i} z_{1j} z_{2l} z_{2m} \int_{k_1} \frac{1}{|\vec{k}_1|^2} \frac{1}{|\vec{k}_1 - \vec{p}_1|^2} [k_1^i k_1^j (k_1 - p_1)^l (k_1 - p_1)^m] \equiv z_{1i} z_{1j} z_{2l} z_{2m} I_C^{ijlm}, \\ D_{z_1, z_2} &= z_{1i} z_{1j} z_{2l} z_{2m} \int_{k_1} \frac{1}{|\vec{k}_1|^2} \frac{1}{|\vec{k}_1 - \vec{p}_1|^2} [k_1^i (k_1 - p_1)^j k_1^l k_1^m] \equiv z_{1i} z_{1j} z_{2l} z_{2m} I_D^{ijlm}, \\ E_{z_1, z_2} &= z_{1i} z_{1j} z_{2l} z_{2m} \int_{k_1} \frac{1}{|\vec{k}_1|^2} \frac{1}{|\vec{k}_1 - \vec{p}_1|^2} [k_1^i (k_1 - p_1)^j (k_1 - p_1)^l (k_1 - p_1)^m] \equiv z_{1i} z_{1j} z_{2l} z_{2m} I_E^{ijlm}, \\ F_{z_1, z_2} &= z_{1i} z_{1j} z_{2l} z_{2m} \int_{k_1} \frac{1}{|\vec{k}_1|^2} \frac{1}{|\vec{k}_1 - \vec{p}_1|^2} [k_1^i (k_1 - p_1)^j k_1^l (k_1 - p_1)^m] \equiv z_{1i} z_{1j} z_{2l} z_{2m} I_F^{ijlm}. \end{aligned} \quad (3.8)$$

We notice that we only have five types of integrals, since $I_F^{ijlm} = I_C^{iljm}$. Furthermore, one can prove that $I_B^{ijlm} = I_A^{ijlm}$ by shifting $\vec{k}_1 \rightarrow \vec{k}_1 = \vec{k}_1 - \vec{p}_1$ and then changing its sign. Along the same lines, one can prove that $I_E^{ijlm} = I_D^{ijlm}$ leaving finally only three integrals to evaluate, namely

$$\begin{aligned} I_1^{ijlm} &= \int_{k_1} \frac{1}{|\vec{k}_1|^2} \frac{1}{|\vec{k}_1 - \vec{p}_1|^2} \left(k_1^i k_1^j k_1^l k_1^m \right), \\ I_2^{ijlm} &= \int_{k_1} \frac{1}{|\vec{k}_1|^2} \frac{1}{|\vec{k}_1 - \vec{p}_1|^2} [k_1^i k_1^j (k_1 - p_1)^l (k_1 - p_1)^m], \\ I_3^{ijlm} &= \int_{k_1} \frac{1}{|\vec{k}_1|^2} \frac{1}{|\vec{k}_1 - \vec{p}_1|^2} [k_1^i (k_1 - p_1)^j k_1^l k_1^m]. \end{aligned} \quad (3.9)$$

The expression (3.7) becomes

$$\langle B_2(p_1|z_1) B_2(p_2|z_2) \rangle = \frac{8}{N} \delta_{\vec{p}_1 + \vec{p}_2} z_{1i} z_{1j} z_{2l} z_{2m} \left(2I_1^{ijlm} + I_2^{ijlm} + I_2^{lmij} + 36I_2^{iljm} + 12I_3^{ijlm} + 12I_3^{lmij} \right). \quad (3.10)$$

Since we are left with a single integrated momentum, we redefine $\vec{k}_1 \equiv \vec{k}$ and we expand the numerators in terms of their powers of \vec{p}_1 to get

$$I_1^{ijlm} = \mathcal{I}_0^{ijlm}, \quad I_2^{ijlm} = \mathcal{I}_0^{ijlm} - \mathcal{I}_1^{ijlm} - \mathcal{I}_1^{ijml} + \mathcal{I}_2^{ijlm}, \quad I_3^{ijlm} = \mathcal{I}_0^{ijlm} - \mathcal{I}_1^{imlj}, \quad (3.11)$$

where we have defined:

$$\begin{aligned} \mathcal{I}_0^{ijlm} &= \int_k \frac{1}{|\vec{k}|^2} \frac{1}{|\vec{k} - \vec{p}_1|^2} \left(k^i k^j k^l k^m \right), \\ \mathcal{I}_1^{ijlm} &= \int_k \frac{1}{|\vec{k}|^2} \frac{1}{|\vec{k} - \vec{p}_1|^2} \left(k^i k^j k^l p_1^m \right), \\ \mathcal{I}_2^{ijlm} &= \int_k \frac{1}{|\vec{k}|^2} \frac{1}{|\vec{k} - \vec{p}_1|^2} \left(k^i k^j p_1^l p_1^m \right). \end{aligned} \quad (3.12)$$

Finally, we arrive at the following minimal expression in terms of the integrals \mathcal{I}_i

$$\begin{aligned} \langle B_2(p_1|z_1) B_2(p_2|z_2) \rangle &= \frac{8}{N} \delta_{\vec{p}_1 + \vec{p}_2} z_{1i} z_{1j} z_{2l} z_{2m} \left[\left(15\mathcal{I}_0^{ijlm} + 13\mathcal{I}_0^{lmij} + 36\mathcal{I}_0^{iljm} \right) \right. \\ &\quad - \left(2\mathcal{I}_1^{ijlm} + 2\mathcal{I}_1^{lmij} + 36\mathcal{I}_1^{ilmj} + 12\mathcal{I}_1^{imlj} + 12\mathcal{I}_1^{ljim} \right) \\ &\quad \left. + \left(\mathcal{I}_2^{ijlm} + \mathcal{I}_2^{lmij} + 36\mathcal{I}_2^{iljm} \right) \right]. \end{aligned} \quad (3.13)$$

3.2.1 Evaluating the integrals and their regularisation

The previous formula (3.13) looks rather cumbersome. At this point, it is convenient to consider the final step one should perform to compute the two-point function of the spin-2 field, that is the shadow transform of the correlator of B_{ij} to a correlator of \mathcal{B}_{ij} . This leads to a simplification of the expression (3.13). The argument goes as follows. We know that the correlator of the boundary fields we are interested in can be found by shadow transforming (3.13) as

$$\langle \mathcal{B}_{2,ij}(p_1) \mathcal{B}_{2,kl}(p_2) \rangle = \frac{1}{p_1^3 p_2^3} \Pi^{i'j'}_{,ij}(\vec{p}_1) \Pi^{k'l'}_{,kl}(\vec{p}_2) \langle B_{2,i'j'}(p_1) B_{2,k'l'}(p_2) \rangle, \quad (3.14)$$

where we have used the inverse of $B_{2,ij}(p) = p^3 \Pi^{i'j'}_{,ij}(\vec{p}) \mathcal{B}_{2,i'j'}(p)$. Once the fictitious contractions with vectors z_i are eliminated, what we are left with is a tensor contraction of propagators $\Pi^{i'j'}_{,ij}(\vec{p}_1) \Pi^{k'l'}_{,kl}(\vec{p}_2)$ with a tensor $T_{i'j'k'l'}$ build out of \vec{p}_1 , \vec{p}_2 and δ_{ij} . The most general tensor

which can be contracted with two projectors, giving a projector as a result, is a projector itself. Namely,

$$\Pi^{i'j'}_{,ij}(\vec{p})\Pi^{k'l'}_{,kl}(\vec{p})\Pi_{i'j',k'l'}(\vec{p}) = \Pi_{ij,kl}(\vec{p}), \quad (3.15)$$

where we used the fact that, in a two point function, the moduli satisfy the relations $p_1 = p_2 = p$. This particular contraction is the only structure which allows for momenta in $T_{i'j',k'l'}$. No other contractions with the momenta are possible since the projector is transverse⁵. We can extract therefore the overall coefficient by computing only the terms proportional to the Kronecker deltas, namely

$$\Pi^{i'j'}_{,ij}(\vec{p}_1)\Pi^{k'l'}_{,kl}(\vec{p}_2) (\delta_{i'k'}\delta_{j'l'}) \quad \text{or} \quad \Pi^{i'j'}_{,ij}(\vec{p}_1)\Pi^{k'l'}_{,kl}(\vec{p}_2) (\delta_{i'l'}\delta_{j'k'}) \quad (3.16)$$

and isolate the term proportional to $(z_1 \cdot z_2)^2$ coming from integrals \mathcal{I}_i which are fully proportional to Dirac deltas. It is straightforward to see that only \mathcal{I}_0 remains

$$\langle B_2(p_1|z_1)B_2(p_2|z_2) \rangle \supset \frac{8}{N} \delta_{\vec{p}_1+\vec{p}_2} z_{1i} z_{1j} z_{2l} z_{2m} \left(15\mathcal{I}_0^{ijlm} + 13\mathcal{I}_0^{lmij} + 36\mathcal{I}_0^{iljm} \right), \quad (3.17)$$

where the inclusion symbol means that, as we just mentioned, we are highlighting only the terms proportional to Kronecker deltas.

The integral \mathcal{I}_0 is divergent. One way to proceed is to compute the two-point function in real space and then Fourier transform it [26, 48–50], as we did in the previous section. Otherwise one can regularise the integral and find the solution by using analytical continuation. More details are provided in Appendix C and E. We define the integral

$$\begin{aligned} \mathcal{I}_0^{ijlm}(d, \delta_1, \delta_2) &= \int \frac{d^d \vec{k}}{(2\pi)^d} \frac{1}{|\vec{k}|^{2\delta_1}} \frac{1}{|\vec{k} - \vec{p}_1|^{2\delta_2}} \left(k^i k^j k^l k^m \right) \\ &\supset \frac{2^{-d+\delta_t-3} \mathcal{S}^{ijlm}}{(4\pi)^{\frac{d}{2}} \Gamma(\delta_1) \Gamma(\delta_2) \Gamma\left(\frac{3d}{2} + 6 - 2\delta_t\right)} I_{d+3-\delta_t\{d-2\delta_t+\delta_1+4, d-2\delta_t+\delta_2+4\}}(p_1, p_2), \end{aligned} \quad (3.18)$$

where $\delta_t = \delta_1 + \delta_2$ and

$$I_{d+3-\delta_t\{d-2\delta_t+\delta_1+4, d-2\delta_t+\delta_2+4\}}(p_1, p_2) = \int_0^\infty dx x^{d+3-\delta_t} \prod_{i=1}^2 p_i^{d-2\delta_t+\delta_i+4} K_{d-2\delta_t+\delta_i+4}(xp_i). \quad (3.19)$$

We recall that the moduli $p_1 = p_2$ due to the momentum conservation, so we define $p = p_1 = p_2$. One can define the following coefficients to match the definition used in Eq. (C.16)

$$\begin{aligned} \alpha &= d + 3 - \delta_t, \\ \beta_1 &= d - 2\delta_t + \delta_1 + 4, \\ \beta_2 &= d - 2\delta_t + \delta_2 + 4. \end{aligned} \quad (3.20)$$

⁵ For example, for the spin-one state (the generalisation to HS is trivial due to the properties of the projector tensors) one can see that

$$\Pi_{ij}\Pi_{kl}\Pi^{jk} = (\delta_{ij} - \hat{p}_i\hat{p}_j)(\delta_{kl} - \hat{p}_k\hat{p}_l) \left(\delta^{jk} - \hat{p}^j\hat{p}^k \right) = (\delta_{ij} - \hat{p}_i\hat{p}_j) \left(\delta_l^j - \hat{p}^j\hat{p}_l \right) = (\delta_{il} - \hat{p}_i\hat{p}_l) = \Pi_{il}.$$

Notice that the same result is achieved by considering only the contraction with the delta such that

$$\Pi_{ij}\Pi_{kl}\delta^{jk} = (\delta_{ij} - \hat{p}_i\hat{p}_j)(\delta_{kl} - \hat{p}_k\hat{p}_l) \delta^{jk} = (\delta_{ij} - \hat{p}_i\hat{p}_j) \left(\delta_l^j - \hat{p}^j\hat{p}_l \right) = (\delta_{il} - \hat{p}_i\hat{p}_l) = \Pi_{il}.$$

The regularisation method prescribes a shift of the weights such that (we leave u and v undetermined following the notations used in Ref. [48] and explained in Appendix E) the solution of the double-K integral is (see Eq. (E.6))

$$\begin{aligned} I_{\alpha+u\epsilon\{\beta_1+v\epsilon,\beta_2+v\epsilon\}}(p,p) &= \frac{2^{\alpha-2+u\epsilon}}{\Gamma(\alpha+1+u\epsilon)p^{\alpha+1-\beta_1-\beta_2+u\epsilon-2v\epsilon}} \Gamma\left(\frac{\alpha+\beta_1+\beta_2+1+u\epsilon+2v\epsilon}{2}\right) \\ &\Gamma\left(\frac{\alpha+\beta_1-\beta_2+1+u\epsilon}{2}\right) \Gamma\left(\frac{\alpha-\beta_1+\beta_2+1+u\epsilon}{2}\right) \Gamma\left(\frac{\alpha-\beta_1-\beta_2+1+u\epsilon-2v\epsilon}{2}\right) \\ &= \frac{2^{2+u\epsilon}}{\Gamma(5+u\epsilon)} p^{3-u\epsilon+2v\epsilon} \Gamma\left(\frac{13}{2} + \frac{(u+2v)\epsilon}{2}\right) \Gamma\left(\frac{5}{2} + \frac{u\epsilon}{2}\right)^2 \Gamma\left(-\frac{3}{2} + \frac{(u-2v)\epsilon}{2}\right), \end{aligned} \quad (3.21)$$

where we have chosen $d = 3$, $\delta_1 = 1$, $\delta_2 = 1$ and $\delta_t = 2$. Sending $\epsilon \rightarrow 0$ we get

$$I_{4,\{4,4\}}(p,p) = \frac{10395\pi^2}{512} p^3 \quad (3.22)$$

so that

$$\mathcal{I}_0^{ijlm}(3,1,1) \supset \frac{2^{-4} S^{ijlm}}{(4\pi)^{\frac{3}{2}} \frac{10395\sqrt{\pi}}{64}} I_{4,\{4,4\}}(p,p) = 2^{-10} p^3 S^{ijlm}. \quad (3.23)$$

3.2.2 Final result

By inserting the expression (3.23) into Eq. (3.17) we finally arrive at

$$\begin{aligned} \langle B_2(p_1|z_1) B_2(p_2|z_2) \rangle &\supset \frac{8}{N} \delta_{\vec{p}_1+\vec{p}_2} z_{1i} z_{1j} z_{2l} z_{2m} 2^{-10} p^3 \left(15 S^{ijlm} + 13 S^{lmij} + 36 S^{iljm} \right) \\ &= \frac{8}{N} \delta_{\vec{p}_1+\vec{p}_2} z_{1i} z_{1j} z_{2l} z_{2m} 2^{-4} p^3 \left(\delta^{ij} \delta^{lm} + \delta^{il} \delta^{jm} + \delta^{im} \delta^{jl} \right). \end{aligned} \quad (3.24)$$

Using the fact that only the terms proportional to $(z_1 \cdot z_2)^2$ survive since the other possible contractions are zero (since z_i are null, *i.e.* $z_i \cdot z_i = 0$, the term proportional to $\delta^{ij} \delta^{lm}$ does not survive), we are left with

$$\langle B_2(p_1|z_1) B_2(p_2|z_2) \rangle \supset \frac{p^3}{N} \delta_{\vec{p}_1+\vec{p}_2} z_{1i} z_{1j} z_{2l} z_{2m} \frac{1}{2} \delta^{il} \delta^{jm}. \quad (3.25)$$

Using now the polynomial prescription we find

$$\langle B_{2,ij}(p_1) B_{2,lm}(p_2) \rangle \supset \frac{p^3}{N} \delta_{\vec{p}_1+\vec{p}_2} \frac{1}{2} \delta_{il} \delta_{jm}, \quad (3.26)$$

which corresponds to the first term of the reconstructed projector tensor. In fact, if one considers all the other possible terms (we do not report here the lengthy, but straightforward calculation), one obtains

$$\langle B_{2,ij}(p_1) B_{2,lm}(p_2) \rangle = \frac{p^3}{N} \Pi_{il,jm}(\vec{p}_1) \delta_{\vec{p}_1+\vec{p}_2}. \quad (3.27)$$

Shadow transforming the previous formula, we find

$$\begin{aligned} \langle \mathcal{B}_{2,ij}(p_1) \mathcal{B}_{2,lm}(p_2) \rangle &= \frac{1}{p_1^3 p_2^3} \Pi^{i'j'}_{,ij}(\vec{p}_1) \Pi^{l'm'}_{,lm}(\vec{p}_2) \langle B_{2,i'j'}(p_1) B_{2,l'm'}(p_2) \rangle \\ &= \frac{1}{N} \frac{1}{p_1^3} \Pi^{i'j'}_{,ij}(\vec{p}_1) \Pi^{l'm'}_{,lm}(\vec{p}_2) \Pi_{i'l',j'm'}(\vec{p}_1) \delta_{\vec{p}_1+\vec{p}_2}. \end{aligned} \quad (3.28)$$

The final result reads

$$\langle \mathcal{B}_{2,ij}(p_1) \mathcal{B}_{2,lm}(p_2) \rangle = \frac{1}{N} \frac{1}{p_1^3} \Pi_{ij,lm}(\vec{p}_1) \delta_{\vec{p}_1 + \vec{p}_2}, \quad (3.29)$$

which coincides with the expression (3.3). The calculation in momentum space is much more complex and lengthy than the one in real space. We have written it in some detail to familiarise the reader with general aspects of the Q -formalism, and provide the necessary tools required for the calculation of the spin-2 three-point correlator.

4 The three-point correlator of the spin-2 field

The three-point function presents a more involved structure. Bulk cubic vertices in Vasiliev theory have been discussed, for example, in [39, 51–54]. We are going to follow the prescription highlighted in the previous sections and used in the computation of the two-point function working directly in momentum space. The three-point function of the spin-2 field can be obtained computing the correlator of three dual fields as in Eq. (2.27) and shadow transforming the result. We start with

$$\begin{aligned} \langle B_2(p_1|z_1) B_2(p_2|z_2) B_2(p_3|z_3) \rangle &= -\frac{16\sqrt{2}}{N^3} \int_{k_1} \int_{k_2} \int_{k_3} \langle :Q_{k_1} Q_{p_1-k_1} :: Q_{k_2} Q_{p_2-k_2} :: Q_{k_3} Q_{p_3-k_3} : \rangle \\ &\quad \times [(z_1 \cdot k_1)^2 + (z_1 \cdot (p_1 - k_1))^2 + 6(z_1 \cdot k_1) z_1 \cdot (k_1 - p_1)] \\ &\quad \times [(z_2 \cdot k_2)^2 + (z_2 \cdot (p_2 - k_2))^2 + 6(z_2 \cdot k_2) z_2 \cdot (k_2 - p_2)] \\ &\quad \times [(z_3 \cdot k_3)^2 + (z_3 \cdot (p_3 - k_3))^2 + 6(z_3 \cdot k_3) z_3 \cdot (k_3 - p_3)]. \end{aligned} \quad (4.1)$$

Following similar steps to those performed in (3.5), the first piece in the integral becomes

$$\langle :Q_{k_1} Q_{p_1-k_1} :: Q_{k_2} Q_{p_2-k_2} :: Q_{k_3} Q_{p_3-k_3} : \rangle = \frac{2N}{2k_1^2 k_2^2 k_3^2} \delta_{\vec{p}_1 - \vec{k}_1 + \vec{k}_2} \delta_{\vec{p}_2 - \vec{k}_2 + \vec{k}_3} \delta_{\vec{p}_3 - \vec{k}_3 + \vec{k}_1}, \quad (4.2)$$

where the $2N$ factor comes from the traces over the $O(2N)$ group indices.

In order to maintain the explicit symmetry under a cyclic permutation of $(\vec{p}_1, \vec{p}_2, \vec{p}_3)$, we symmetrise by adding 1/3 times each of the three equivalent choices of deltas. The three choices are the following

$$\begin{aligned} \text{(a)} \quad & \vec{k}_2 = \vec{k}_1 - \vec{p}_1, \quad \vec{k}_3 = \vec{k}_1 + \vec{p}_3, \\ \text{(b)} \quad & \vec{k}_1 = \vec{k}_3 - \vec{p}_3, \quad \vec{k}_2 = \vec{k}_3 + \vec{p}_2, \\ \text{(c)} \quad & \vec{k}_1 = \vec{k}_2 + \vec{p}_1, \quad \vec{k}_3 = \vec{k}_2 - \vec{p}_2. \end{aligned} \quad (4.3)$$

We perform two integrals using the delta functions and reconstruct the external momentum conservation $\delta_{\vec{p}_1 + \vec{p}_2 + \vec{p}_3}$. After some manipulations we obtain

$$\begin{aligned} \langle B_2(p_1|z_1) B_2(p_2|z_2) B_2(p_3|z_3) \rangle &= -\frac{32\sqrt{2}}{3N^2} \delta_{\vec{p}_1 + \vec{p}_2 + \vec{p}_3} \int_k \frac{1}{k^2} \frac{1}{|\vec{k} - \vec{p}_1|^2} \frac{1}{|\vec{k} + \vec{p}_2|^2} \\ &\quad \times [(z_1 \cdot (k - p_1))^2 + (z_1 \cdot k)^2 + 6(z_1 \cdot k) z_1 \cdot (k - p_1)] \\ &\quad \times [(z_2 \cdot k)^2 + (z_2 \cdot (k + p_2))^2 + 6(z_2 \cdot k) z_2 \cdot (k + p_2)] \\ &\quad \times [(z_3 \cdot (k + p_2))^2 + (z_3 \cdot (k - p_1))^2 + 6z_3 \cdot (k + p_2) (z_3 \cdot (k - p_1))] \\ &\quad + \text{all with } (p_1 \rightarrow p_3, p_2 \rightarrow p_1, p_3 \rightarrow p_2, z_1 \rightarrow z_3, z_2 \rightarrow z_1, z_3 \rightarrow z_2) \\ &\quad + \text{all with } (p_1 \rightarrow p_2, p_2 \rightarrow p_3, p_3 \rightarrow p_1, z_1 \rightarrow z_2, z_2 \rightarrow z_3, z_3 \rightarrow z_1). \end{aligned} \quad (4.4)$$

After fully expanding this expression (containing 54 terms + cyclic permutations), we can identify the following set of independent integrals (the lower index identifies the number of k 's in the integrals)

$$\mathcal{I}_{r,q_1q_2}^{i_1 \dots i_r} = \int_k \frac{1}{k^2} \frac{1}{|\vec{k} - \vec{q}_1|^2} \frac{1}{|\vec{k} + \vec{q}_2|^2} (k^{i_1} \dots k^{i_r}). \quad (4.5)$$

Notice that, by construction, the integrals $\mathcal{I}_{r,q_1q_2}^{i_1 \dots i_r}$ are symmetric under the exchange of any couple of indices. Equation (4.4) then can be written as

$$\begin{aligned} \langle B_2(p_1|z_1)B_2(p_2|z_2)B_2(p_3|z_3) \rangle = & -\frac{32\sqrt{2}}{3N^2} \delta_{\vec{p}_1+\vec{p}_2+\vec{p}_3} \left[z_{1a}z_{1b}z_{2i}z_{2j}z_{3m}z_{3n} \left(512 \mathcal{I}_{6,p_1p_2}^{abijmn} \right. \right. \\ & - 512 \mathcal{I}_{5,p_1p_2}^{abijm} p_1^n + 512 \mathcal{I}_{5,p_1p_2}^{abijm} p_2^n + 64 \mathcal{I}_{4,p_1p_2}^{abij} p_1^m p_1^n - 384 \mathcal{I}_{4,p_1p_2}^{abij} p_1^m p_2^n + 64 \mathcal{I}_{4,p_1p_2}^{abij} p_2^m p_2^n \\ & + 512 \mathcal{I}_{5,p_1p_2}^{abimn} p_2^j - 512 \mathcal{I}_{4,p_1p_2}^{abim} p_1^n p_2^j + 512 \mathcal{I}_{4,p_1p_2}^{abim} p_2^j p_2^n + 64 \mathcal{I}_{3,p_1p_2}^{abi} p_1^m p_1^n p_2^j \\ & - 384 \mathcal{I}_{3,p_1p_2}^{abi} p_1^m p_2^j p_2^n + 64 \mathcal{I}_{3,p_1p_2}^{abi} p_2^j p_2^m p_2^n + 64 \mathcal{I}_{4,p_1p_2}^{abmn} p_2^i p_2^j - 64 \mathcal{I}_{3,p_1p_2}^{abm} p_1^n p_2^i p_2^j \\ & + 64 \mathcal{I}_{3,p_1p_2}^{abm} p_2^i p_2^j p_2^n + 8 \mathcal{I}_{2,p_1p_2}^{ab} p_1^m p_1^n p_2^i p_2^j - 48 \mathcal{I}_{2,p_1p_2}^{ab} p_1^m p_2^i p_2^j p_2^n + 8 \mathcal{I}_{2,p_1p_2}^{ab} p_2^i p_2^j p_2^m p_2^n \\ & - 512 \mathcal{I}_{5,p_1p_2}^{aijmn} p_1^b + 512 \mathcal{I}_{4,p_1p_2}^{aijmn} p_1^b p_1^n - 512 \mathcal{I}_{4,p_1p_2}^{aijmn} p_1^b p_2^n - 64 \mathcal{I}_{3,p_1p_2}^{aij} p_1^b p_1^m p_1^n \\ & + 384 \mathcal{I}_{3,p_1p_2}^{aij} p_1^b p_1^m p_2^n - 64 \mathcal{I}_{3,p_1p_2}^{aij} p_1^b p_2^m p_2^n - 512 \mathcal{I}_{4,p_1p_2}^{aimn} p_1^b p_2^j + 512 \mathcal{I}_{3,p_1p_2}^{aim} p_1^b p_1^n p_2^j \\ & - 512 \mathcal{I}_{3,p_1p_2}^{aim} p_1^b p_2^j p_2^n - 64 \mathcal{I}_{2,p_1p_2}^{ai} p_1^b p_1^m p_1^n p_2^j + 384 \mathcal{I}_{2,p_1p_2}^{ai} p_1^b p_1^m p_2^j p_2^n - 64 \mathcal{I}_{2,p_1p_2}^{ai} p_1^b p_2^j p_2^m p_2^n \\ & - 64 \mathcal{I}_{3,p_1p_2}^{amn} p_1^b p_2^i p_2^j + 64 \mathcal{I}_{2,p_1p_2}^{am} p_1^b p_1^n p_2^i p_2^j - 64 \mathcal{I}_{2,p_1p_2}^{am} p_1^b p_2^i p_2^j p_2^n - 8 \mathcal{I}_{1,p_1p_2}^a p_1^b p_1^m p_1^n p_2^i p_2^j \\ & + 48 \mathcal{I}_{1,p_1p_2}^a p_1^b p_1^m p_2^i p_2^j p_2^n - 8 \mathcal{I}_{1,p_1p_2}^a p_1^b p_2^i p_2^j p_2^m p_2^n + 64 \mathcal{I}_{4,p_1p_2}^{ijmn} p_1^a p_1^b - 64 \mathcal{I}_{3,p_1p_2}^{ijm} p_1^a p_1^b p_1^n \\ & + 64 \mathcal{I}_{3,p_1p_2}^{ijm} p_1^a p_1^b p_2^n + 8 \mathcal{I}_{2,p_1p_2}^{ij} p_1^a p_1^b p_1^m p_1^n - 48 \mathcal{I}_{2,p_1p_2}^{ij} p_1^a p_1^b p_1^m p_2^n + 8 \mathcal{I}_{2,p_1p_2}^{ij} p_1^a p_1^b p_2^m p_2^n \\ & + 64 \mathcal{I}_{3,p_1p_2}^{imn} p_1^a p_1^b p_2^j - 64 \mathcal{I}_{2,p_1p_2}^{im} p_1^a p_1^b p_1^n p_2^j + 64 \mathcal{I}_{2,p_1p_2}^{im} p_1^a p_1^b p_2^j p_2^n + 8 \mathcal{I}_{1,p_1p_2}^i p_1^a p_1^b p_1^m p_1^n p_2^j \\ & - 48 \mathcal{I}_{1,p_1p_2}^i p_1^a p_1^b p_1^m p_2^j p_2^n + 8 \mathcal{I}_{1,p_1p_2}^i p_1^a p_1^b p_2^j p_2^m p_2^n + 8 \mathcal{I}_{2,p_1p_2}^{mn} p_1^a p_1^b p_2^i p_2^j - 8 \mathcal{I}_{1,p_1p_2}^m p_1^a p_1^b p_1^n p_2^i p_2^j \\ & + 8 \mathcal{I}_{1,p_1p_2}^m p_1^a p_1^b p_2^i p_2^j p_2^n + \mathcal{I}_{0,p_1p_2}^a p_1^b p_1^m p_1^n p_2^i p_2^j - 6 \mathcal{I}_{0,p_1p_2}^a p_1^b p_1^m p_2^i p_2^j p_2^n + \mathcal{I}_{0,p_1p_2}^a p_1^b p_2^i p_2^j p_2^m p_2^n \Big) \\ & + \text{all with } (p_1 \rightarrow p_3, p_2 \rightarrow p_1, p_3 \rightarrow p_2, z_1 \rightarrow z_3, z_2 \rightarrow z_1, z_3 \rightarrow z_2) \\ & + \text{all with } (p_1 \rightarrow p_2, p_2 \rightarrow p_3, p_3 \rightarrow p_1, z_1 \rightarrow z_2, z_2 \rightarrow z_3, z_3 \rightarrow z_1) \Big]. \quad (4.6) \end{aligned}$$

At this point we can get rid of the z_i following the polynomial prescription as in Eq. (2.28).

4.1 The general structure

First, let us consider the most general structure expected to be found. The general form of a three-point function of spin-2 fields is known in literature (see for example Ref. [48]) and it is of the form

$$\langle B_{2,ab}(p_1)B_{2,ij}(p_2)B_{3,mn}(p_3) \rangle = \langle t_{ab}(p_1)t_{ij}(p_2)t_{mn}(p_3) \rangle + \text{longitudinal and trace terms}, \quad (4.7)$$

where $t_{ab}(p_1) = \Pi^{a'b'}_{,ab}(\vec{p}_1)B_{2,a'b'}(p_1)$, identifying the transverse and traceless component of the spin-2 dual field. Reconstructing the full expression can be done in principle, but it can be very hard in practice. Since we are interested in the three-point function of spin-2 fields, we perform the shadow transform which requires a contraction with three projectors as in Eq. (B.6)

$$\langle \mathcal{B}_{2,ab}(p_1)\mathcal{B}_{2,ij}(p_2)\mathcal{B}_{3,mn}(p_3) \rangle = \frac{1}{p_1^3 p_2^3 p_3^3} \Pi^{a'b'}_{,ab}(\vec{p}_1) \Pi^{i'j'}_{,ij}(\vec{p}_2) \Pi^{m'n'}_{,mn}(\vec{p}_3) \langle B_{2,a'b'}(p_1)B_{2,i'j'}(p_2)B_{2,m'n'}(p_3) \rangle. \quad (4.8)$$

The projectors select the transverse and traceless part and we get

$$\begin{aligned}
\langle \mathcal{B}_{2,ab}(p_1) \mathcal{B}_{2,ij}(p_2) \mathcal{B}_{3,mn}(p_3) \rangle &= \frac{1}{p_1^3 p_2^3 p_3^3} \delta_{\vec{p}_1 + \vec{p}_2 + \vec{p}_3} \Pi_{ab,i_1 i_2}(\vec{p}_1) \Pi_{ij,i_3 i_4}(\vec{p}_2) \Pi_{mn,i_5 i_6}(\vec{p}_3) \\
&\left[A_1 p_2^{i_1} p_2^{i_2} p_3^{i_3} p_3^{i_4} p_1^{i_5} p_1^{i_6} \right. \\
&+ A_2 \delta^{i_2 i_4} p_2^{i_1} p_3^{i_3} p_1^{i_5} p_1^{i_6} + A_2 (p_1 \leftrightarrow p_3) \delta^{i_4 i_6} p_2^{i_1} p_2^{i_2} p_3^{i_3} p_1^{i_5} + A_2 (p_2 \leftrightarrow p_3) \delta^{i_2 i_6} p_2^{i_1} p_3^{i_3} p_3^{i_4} p_1^{i_5} \quad (4.9) \\
&+ A_3 \delta^{i_1 i_3} \delta^{i_2 i_4} p_1^{i_5} p_1^{i_6} + A_3 (p_1 \leftrightarrow p_3) \delta^{i_3 i_5} \delta^{i_4 i_6} p_2^{i_1} p_2^{i_2} + A_3 (p_2 \leftrightarrow p_3) \delta^{i_1 i_5} \delta^{i_2 i_6} p_3^{i_3} p_3^{i_4} \\
&+ A_4 \delta^{i_1 i_5} \delta^{i_3 i_6} p_2^{i_2} p_3^{i_4} + A_4 (p_1 \leftrightarrow p_3) \delta^{i_1 i_5} \delta^{i_3 i_2} p_3^{i_4} p_1^{i_6} + A_4 (p_2 \leftrightarrow p_3) \delta^{i_1 i_3} \delta^{i_5 i_4} p_2^{i_2} p_1^{i_6} \\
&\left. + A_5 \delta^{i_1 i_4} \delta^{i_3 i_6} \delta^{i_5 i_2} \right].
\end{aligned}$$

Therefore, by applying the three projectors on $\langle B_{2,ab}(p_1) B_{2,ij}(p_2) B_{3,mn}(p_3) \rangle$ given by Eq. (4.6), one can identify the coefficients A_i . In practice, in Eq. (4.6), we can neglect terms which contains $\delta_{a'b'}$, $\delta_{i'j'}$ and $\delta_{m'n'}$, given that they were already zero since $z_1^2 = z_2^2 = z_3^2 = 0$. Furthermore, we can neglect pieces which would give rise to contractions of the form

$$\vec{p}_1 \cdot \Pi(\vec{p}_1) = 0, \quad \vec{p}_2 \cdot \Pi(\vec{p}_2) = 0, \quad \vec{p}_3 \cdot \Pi(\vec{p}_3) = 0, \quad (4.10)$$

since the projector is transverse by construction.

4.2 Result

The symmetry properties of the correlator outlined in the previous subsection lead to a simplification of Eq. (4.6), which becomes

$$\begin{aligned}
\langle B_2^{ab}(p_1) B_2^{ij}(p_2) B_3^{mn}(p_3) \rangle &\supset -\frac{32\sqrt{2}}{3N^2} \delta_{\vec{p}_1 + \vec{p}_2 + \vec{p}_3} \left[64 p_1^{mn} \mathcal{I}_{4,p_1 p_2}^{abij} - 384 p_1^m p_2^n \mathcal{I}_{4,p_1 p_2}^{abij} \right. \\
&+ 64 p_2^{mn} \mathcal{I}_{4,p_1 p_2}^{abij} + 64 p_1^{ij} \mathcal{I}_{4,p_1 p_3}^{abmn} - 384 p_1^i p_3^j \mathcal{I}_{4,p_1 p_3}^{abmn} + 64 p_3^{ij} \mathcal{I}_{4,p_1 p_3}^{abmn} \\
&+ 64 p_2^{ab} \mathcal{I}_{4,p_2 p_3}^{ijmn} - 384 p_2^a p_3^b \mathcal{I}_{4,p_2 p_3}^{ijmn} + 64 p_3^{ab} \mathcal{I}_{4,p_2 p_3}^{ijmn} - 512 p_1^n \mathcal{I}_{5,p_1 p_2}^{abijm} \quad (4.11) \\
&+ 512 p_2^n \mathcal{I}_{5,p_1 p_2}^{abijm} + 512 p_1^j \mathcal{I}_{5,p_1 p_3}^{abimn} - 512 p_3^j \mathcal{I}_{5,p_1 p_3}^{abimn} - 512 p_2^b \mathcal{I}_{5,p_2 p_3}^{aijmn} \\
&\left. + 512 p_3^b \mathcal{I}_{5,p_2 p_3}^{aijmn} + 512 \mathcal{I}_{6,p_1 p_2}^{abijmn} + 512 \mathcal{I}_{6,p_1 p_3}^{abijmn} + 512 \mathcal{I}_{6,p_2 p_3}^{abijmn} \right].
\end{aligned}$$

The previous expression is fully symmetric under a cyclic permutation of the external momenta as required by construction. The structure in Eq. (4.9) is fully recovered and, after a substitution of the integrals computed in Appendix D.1, the coefficients are found to be

$$\begin{aligned}
A_1 &= -\frac{32 \cdot 8192 \sqrt{2}}{3N^2} (i_{3,4,\{1,3,3\}} + i_{3,4,\{3,1,3\}} + i_{3,4,\{3,3,1\}} - 4 i_{3,5,\{1,3,4\}} \\
&- 4 i_{3,5,\{1,4,3\}} - 4 i_{3,5,\{3,1,4\}} - 4 i_{3,5,\{3,4,1\}} - 4 i_{3,5,\{4,1,3\}} \\
&- 4 i_{3,5,\{4,3,1\}} + 4 i_{3,6,\{1,3,5\}} + 8 i_{3,6,\{1,4,4\}} + 4 i_{3,6,\{1,5,3\}} \\
&+ 4 i_{3,6,\{3,1,5\}} + 4 i_{3,6,\{3,5,1\}} + 8 i_{3,6,\{4,1,4\}} + 8 i_{3,6,\{4,4,1\}} \\
&+ 4 i_{3,6,\{5,1,3\}} + 4 i_{3,6,\{5,3,1\}}), \quad (4.12a)
\end{aligned}$$

$$\begin{aligned}
A_2 &= -\frac{32 \cdot 8192 \sqrt{2}}{3N^2} (i_{3,3,\{2,2,1\}} + 2 i_{3,4,\{1,2,3\}} + 2 i_{3,4,\{2,1,3\}} - 4 i_{3,4,\{2,3,1\}} \\
&- 4 i_{3,4,\{3,2,1\}} - 4 i_{3,5,\{1,2,4\}} - 4 i_{3,5,\{1,3,3\}} - 4 i_{3,5,\{2,1,4\}} \\
&+ 4 i_{3,5,\{2,4,1\}} - 4 i_{3,5,\{3,1,3\}} + 8 i_{3,5,\{3,3,1\}} + 4 i_{3,5,\{4,2,1\}}), \quad (4.12b)
\end{aligned}$$

$$A_3 = -\frac{32 \cdot 1024\sqrt{2}}{3N^2} (i_{3,2,\{1,1,1\}} - 4i_{3,3,\{1,2,1\}} - 4i_{3,3,\{2,1,1\}} + 8i_{3,4,\{1,1,3\}} + 4i_{3,4,\{1,3,1\}} + 4i_{3,4,\{2,2,1\}} + 4i_{3,4,\{3,1,1\}}), \quad (4.12c)$$

$$A_4 = -\frac{32 \cdot 8192\sqrt{2}}{3N^2} (i_{3,3,\{1,2,1\}} + i_{3,3,\{2,1,1\}} - 2i_{3,4,\{1,2,2\}} - 2i_{3,4,\{1,3,1\}} - 2i_{3,4,\{2,1,2\}} + 2i_{3,4,\{2,2,1\}} - 2i_{3,4,\{3,1,1\}}), \quad (4.12d)$$

$$A_5 = -\frac{32 \cdot 12288\sqrt{2}}{3N^2} i_{3,3,\{1,1,1\}}, \quad (4.12e)$$

where $i_{3,m,\{n_1,n_2,n_3\}}$ are defined in Eq. (D.4). The coefficients A_1, A_5 are symmetric under the cyclic permutation of the external momenta, while the coefficients A_2, A_3, A_4 are symmetric under the exchange $\vec{p}_1 \leftrightarrow \vec{p}_2$. The integrals in A_1, A_2 are all convergent, so they can easily be computed using the formulas shown in Appendix D. However A_3, A_4, A_5 contain only divergent integrals for which we need to use the regularisation procedure as described in Appendix E.

Our final result is

$$\begin{aligned} A_1 &= C_1 \frac{8}{a_{123}^6} [a_{123}^3 + 3a_{123}b_{123} + 15c_{123}], \\ A_2 &= C_1 \frac{8}{a_{123}^5} [4p_3^4 + 20p_3^3a_{12} + 4p_3^2(7a_{12}^2 + 6b_{12}) + 15p_3a_{12}(a_{12}^2 + b_{12}) + 3a_{12}^2(a_{12}^2 + b_{12})], \\ A_3 &= C_1 \frac{2p_3^2}{a_{123}^4} [7p_3^3 + 28p_3^2a_{12} + 3p_3(11a_{12}^2 + 6b_{12}) + 12a_{12}(a_{12}^2 + b_{12})] \\ &\quad - C_2 \frac{8\sqrt{\pi}}{3a_{123}^2} [a_{123}^3 - a_{123}b_{123} - c_{123}], \\ A_4 &= C_1 \frac{4}{a_{123}^4} [-3p_3^5 - 12p_3^4a_{12} - 9p_3^3(a_{12}^2 + 2b_{12}) + 9p_3^2a_{12}(a_{12}^2 - 3b_{12}) \\ &\quad + (4p_3 + a_{12})(3a_{12}^4 - 3a_{12}^2b_{12} + 4b_{12}^2)] - C_2 \frac{16\sqrt{\pi}}{3a_{123}^2} [a_{123}^3 - a_{123}b_{123} - c_{123}], \\ A_5 &= C_1 \frac{2}{a_{123}^3} [-3a_{123}^6 + 9a_{123}^4b_{123} + 12a_{123}^2b_{123}^2 - 33a_{123}^3c_{123} + 12a_{123}b_{123}c_{123} + 8c_{123}^2] \\ &\quad + C_2 \frac{8}{3}\sqrt{\pi}(p_1^3 + p_2^3 + p_3^3), \end{aligned} \quad (4.13)$$

where

$$C_1 = -\frac{8\sqrt{2}}{15N^2}, \quad C_2 = -\frac{6\sqrt{2}}{\sqrt{\pi}N^2}, \quad (4.14)$$

and we have used the following compact notation for the external momenta

$$\begin{aligned} a_{123} &= p_1 + p_2 + p_3, & b_{123} &= p_1p_2 + p_1p_3 + p_2p_3, & c_{123} &= p_1p_2p_3, \\ a_{ij} &= p_i + p_j, & b_{ij} &= p_ip_j, \end{aligned}$$

with $i, j = 1, 2, 3$. As a sanity check for the coefficients of the three-point function of the spin-2 field, we have controlled that they correctly satisfy the primary conformal Ward identities as outlined in Ref. [48].

5 The three-point correlator as Einstein plus (Weyl)³

We are now in the position to elaborate further about the three-point correlator of the spin-2 field. In the introduction we reminded the reader that general symmetric arguments impose that the three-point correlator of the spin-2 field must be a combination of the three-point correlators induced by the Einstein and the (Weyl)³ terms in the action. Given the complexity of the formulae (4.9) and (4.13), this looks miraculous, but it is indeed a beautiful example of symmetry in action.

We define the spin-2 field as

$$\mathcal{B}_{2,ij}(\eta, \vec{x}) = \sum_{\lambda} \int_k \epsilon_{ij}^{\lambda}(\vec{k}) \mathcal{B}_k^{\lambda}(\eta) e^{i\vec{k}\cdot\vec{x}}. \quad (5.1)$$

By shadow transforming the results of the previous section and using the property of the projector tensor in Eq. (A.3),

$$\epsilon_{ab}^{*\lambda_1}(\vec{p}_1) \Pi^{ab}{}_{,j_1 j_2}(\vec{p}_1) = \epsilon_{j_1 j_2}^{*\lambda_1}(\vec{p}_1), \quad (5.2)$$

we obtain

$$\langle \mathcal{B}_{\vec{p}_1}^{\lambda_1} \mathcal{B}_{\vec{p}_2}^{\lambda_2} \mathcal{B}_{\vec{p}_3}^{\lambda_3} \rangle = \epsilon_{ab}^{*\lambda_1}(\vec{p}_1) \epsilon_{ij}^{*\lambda_2}(\vec{p}_2) \epsilon_{mn}^{*\lambda_3}(\vec{p}_3) \langle \mathcal{B}_2^{ab}(p_1) \mathcal{B}_2^{ij}(p_2) \mathcal{B}_3^{mn}(p_3) \rangle. \quad (5.3)$$

Upon defining the following quantities

$$\begin{aligned} \mathcal{E}_1^{\lambda}(\vec{k}_1 | \vec{k}_2, \vec{k}_3) &= \epsilon_{ij}^{*\lambda}(\vec{k}_1) k_2^i k_3^j, \\ \mathcal{E}_2^{\lambda_1 \lambda_2}(\vec{k}_1, \vec{k}_2 | \vec{k}_3, \vec{k}_4) &= \epsilon_{ik}^{*\lambda_1}(\vec{k}_1) \epsilon_j^{*\lambda_2, k}(\vec{k}_2) k_3^i k_4^j, \\ \mathcal{E}_3^{\lambda_1 \lambda_2}(\vec{k}_1, \vec{k}_2) &= \epsilon_{ij}^{*\lambda_1}(\vec{k}_1) \epsilon^{*\lambda_2, ij}(\vec{k}_2), \\ \mathcal{E}_4^{\lambda_1 \lambda_2 \lambda_3}(\vec{k}_1, \vec{k}_2, \vec{k}_3 | \vec{k}_4, \vec{k}_5) &= \epsilon_{ij}^{*\lambda_1}(\vec{k}_1) \epsilon_{kl}^{*\lambda_2}(\vec{k}_2) \epsilon^{*\lambda_3, ik}(\vec{k}_3) k_4^j k_5^l, \\ \mathcal{E}_5^{\lambda_1 \lambda_2 \lambda_3}(\vec{k}_1, \vec{k}_2, \vec{k}_3) &= \epsilon_{ij}^{*\lambda_1}(\vec{k}_1) \epsilon_k^{*\lambda_2, i}(\vec{k}_2) \epsilon^{*\lambda_3, jk}(\vec{k}_3), \end{aligned} \quad (5.4)$$

we can rewrite the three-point correlator as

$$\begin{aligned} \langle \mathcal{B}_{\vec{p}_1}^{\lambda_1} \mathcal{B}_{\vec{p}_2}^{\lambda_2} \mathcal{B}_{\vec{p}_3}^{\lambda_3} \rangle &= \frac{1}{p_1^3 p_2^3 p_3^3} \delta_{\vec{p}_1 + \vec{p}_2 + \vec{p}_3} \left[A_1 \mathcal{E}_1^{\lambda_1}(\vec{p}_1 | \vec{p}_2, \vec{p}_2) \mathcal{E}_1^{\lambda_2}(\vec{p}_2 | \vec{p}_3, \vec{p}_3) \mathcal{E}_1^{\lambda_3}(\vec{p}_3 | \vec{p}_1, \vec{p}_1) \right. \\ &+ A_2 \mathcal{E}_2^{\lambda_1 \lambda_2}(\vec{p}_1, \vec{p}_2 | \vec{p}_2, \vec{p}_3) \mathcal{E}_1^{\lambda_3}(\vec{p}_3 | \vec{p}_1, \vec{p}_1) + A_2(p_1 \leftrightarrow p_3) \mathcal{E}_2^{\lambda_2 \lambda_3}(\vec{p}_2, \vec{p}_3 | \vec{p}_3, \vec{p}_1) \mathcal{E}_1^{\lambda_1}(\vec{p}_1 | \vec{p}_2, \vec{p}_2) \\ &+ A_2(p_2 \leftrightarrow p_3) \mathcal{E}_2^{\lambda_1 \lambda_3}(\vec{p}_1, \vec{p}_3 | \vec{p}_2, \vec{p}_1) \mathcal{E}_1^{\lambda_2}(\vec{p}_2 | \vec{p}_3, \vec{p}_3) + A_3 \mathcal{E}_3^{\lambda_1 \lambda_2}(\vec{p}_1, \vec{p}_2) \mathcal{E}_1^{\lambda_3}(\vec{p}_3 | \vec{p}_1, \vec{p}_1) \\ &+ A_3(p_1 \leftrightarrow p_3) \mathcal{E}_3^{\lambda_2 \lambda_3}(\vec{p}_2, \vec{p}_3) \mathcal{E}_1^{\lambda_1}(\vec{p}_1 | \vec{p}_2, \vec{p}_2) + A_3(p_2 \leftrightarrow p_3) \mathcal{E}_3^{\lambda_1 \lambda_3}(\vec{p}_1, \vec{p}_3) \mathcal{E}_1^{\lambda_2}(\vec{p}_2 | \vec{p}_3, \vec{p}_3) \\ &+ A_4 \mathcal{E}_4^{\lambda_1 \lambda_2 \lambda_3}(\vec{p}_1, \vec{p}_2, \vec{p}_3 | \vec{p}_2, \vec{p}_3) + A_4(p_1 \leftrightarrow p_3) \mathcal{E}_4^{\lambda_3 \lambda_2 \lambda_1}(\vec{p}_3, \vec{p}_2, \vec{p}_1 | \vec{p}_1, \vec{p}_3) \\ &+ A_4(p_2 \leftrightarrow p_3) \mathcal{E}_4^{\lambda_1 \lambda_3 \lambda_2}(\vec{p}_1, \vec{p}_3, \vec{p}_2 | \vec{p}_2, \vec{p}_1) + A_5 \mathcal{E}_5^{\lambda_1 \lambda_2 \lambda_3}(\vec{p}_1, \vec{p}_2, \vec{p}_3) \Big]. \end{aligned} \quad (5.5)$$

In Appendices F and G we provide the explicit expressions for these structures in the X and P basis and in the chiral basis, respectively. We use here the same notation of Ref. [32] for the X and P basis (usually dubbed the $\{\times, +\}$ basis).

We note that the last term in the coefficient A_5 of Eq. (4.13) (the piece proportional to C_2) is a contact term and it parametrises the ambiguity in the definition of the spin-2 field. Indeed, it can always be removed upon redefining the \mathcal{B}_{ij} field by $\mathcal{B}_{ij} \rightarrow \mathcal{B}_{ij} + c \mathcal{B}_{ik} \mathcal{B}_j^k$ (c being a constant), see for instance the discussion in Ref. [32].⁶ We disregard it from now on.

⁶Notice that the contact terms are necessary to reproduce the exact squeezed limit of the graviton three-point functions from the stress tensor three-point function [55, 56]. We thank P. McFadden and K. Skenderis for discussions about this point.

We define the quantities

$$\begin{aligned} J(p_1, p_2, p_3) &= 2(p_1^2 p_2^2 + p_1^2 p_3^2 + p_2^2 p_3^2) - (p_1^4 + p_2^4 + p_3^4), \\ I(p_1, p_2, p_3) &= \left(p_1 + p_2 + p_3 - \frac{(p_1 p_2 + p_1 p_3 + p_2 p_3)}{p_1 + p_2 + p_3} - \frac{p_1 p_2 p_3}{(p_1 + p_2 + p_3)^2} \right), \end{aligned} \quad (5.6)$$

to construct the following shapes

$$\begin{aligned} E^{PPP}(p_1, p_2, p_3) &= \frac{J(p_1, p_2, p_3)}{4(p_1 p_2 p_3)^5} \left(\sum_{i=1}^3 p_i^4 + 6 \sum_{i < j} p_i^2 p_j^2 \right) I(p_1, p_2, p_3), \\ E^{XXP}(p_1, p_2, p_3) &= \frac{J(p_1, p_2, p_3)}{(p_1 p_2 p_3)^4} \frac{p_1^2 + p_2^2 + 3p_3^2}{p_3} I(p_1, p_2, p_3), \\ W^{3PPP}(p_1, p_2, p_3) &= 270 \frac{(p_1 + p_2 - p_3)(p_2 + p_3 - p_1)(p_3 + p_1 - p_2)}{(p_1 + p_2 + p_3)^3 (p_1 p_2 p_3)^2}, \\ W^{3XXP}(p_1, p_2, p_3) &= -W^{3PPP}(p_1, p_2, p_3). \end{aligned} \quad (5.7)$$

They represent the shapes from the Einstein term and the $(\text{Weyl})^3$ term of the three-point correlators [32]. Using the tensorial contractions in Appendix F, we can now write the long expression for the three-point correlators from the higher-spin gravity in a simple and compact form⁷

$$\begin{aligned} \langle \mathcal{B}_{\vec{p}_1}^P \mathcal{B}_{\vec{p}_2}^P \mathcal{B}_{\vec{p}_3}^P \rangle' &= -\frac{2}{N^2} E^{PPP}(p_1, p_2, p_3) + \frac{8}{270 N^2} W^{3PPP}(p_1, p_2, p_3), \\ \langle \mathcal{B}_{\vec{p}_1}^X \mathcal{B}_{\vec{p}_2}^X \mathcal{B}_{\vec{p}_3}^P \rangle' &= \frac{2}{N^2} E^{XXP}(p_1, p_2, p_3) + \frac{8}{270 N^2} W^{3XXP}(p_1, p_2, p_3), \end{aligned} \quad (5.8)$$

where we have used the standard notation for which the $\langle \dots \rangle'$ indicates that the factor $(2\pi)^3$ times the Dirac delta has been removed.

Thus, we have established that the three-point correlator for the spin-2 field in Vasiliev's higher-spin minimal bosonic theory are a combination of two pieces, one coming from the Einstein term and the other from the $(\text{Weyl})^3$ term, once the contact terms have been properly removed. Notice also that, even though shape-dependent, the $(\text{Weyl})^3$ is parametrically of the same order of the Einstein term. Using the gravitational action (1.1), one finds that the ratio of the $(\text{Weyl})^3$ -to-the-Einstein contributions is (up to the shapes) equal to $(HL)^4/2$ [32]. From our results we infer that

$$HL = \left(\frac{8}{270} \right)^{1/4} \simeq 0.4. \quad (5.9)$$

The scale L gives a measure of the size of higher derivative corrections and in higher-spin gravity this length scale turns out to be rather sizeable. In Fig. 2 we plot the ratio of the contribution from the $(\text{Weyl})^3$ and the Einstein term, as a function of the ratios $r_2 = p_2/p_1$, $r_3 = p_3/p_1$

$$\mathcal{R}^{PPP}(r_2, r_3) = \frac{W^{3PPP}(p_1, p_2, p_3)}{E^{PPP}(p_1, p_2, p_3)} \quad \text{and} \quad \mathcal{R}^{XXP}(r_2, r_3) = \frac{W^{3XXP}(p_1, p_2, p_3)}{E^{XXP}(p_1, p_2, p_3)}. \quad (5.10)$$

The previous quantities are independent of p_1 . We see that this ratio is maximised for the so-called equilateral configuration, where all the momenta are equal. This makes sense as the $(\text{Weyl})^3$ term depends on gradients of the spin-2 field.

We dedicate the next section to a more refined discussion of the shapes of the three-point correlator for the spin-2 field.

⁷This simplification can be also understood as originated by the tensorial degeneracies which exist in three dimensions, see for instance Ref. [48].

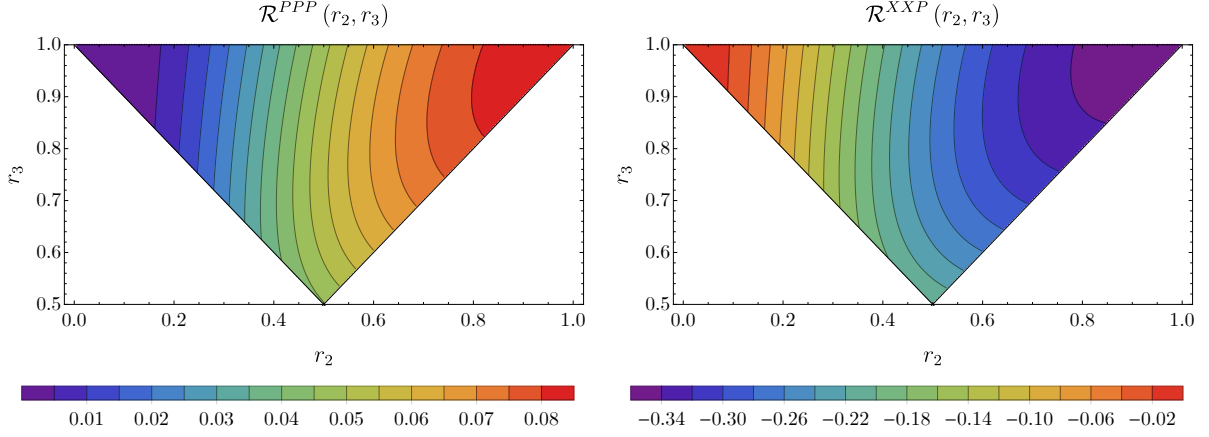


Figure 2. Ratios $\mathcal{R}^{\lambda_1, \lambda_2, \lambda_3}(r_2, r_3)$ as defined in Eq. (5.10).

6 The shapes of the graviton three-point correlator

In this section we wish to analyse the possible shape configurations of the graviton three-point correlator. In order to make contact with the majority of the literature, we do so in the chiral basis, see Appendix G, where the helicity R corresponds to $\lambda = 1$ and the helicity L corresponds to $\lambda = -1$. We may consider two different limits.

6.1 The squeezed limit

In the squeezed limit we take $p_1 \ll p_2, p_3$ and obtain

$$\left\langle \mathcal{B}_{\vec{p}_1}^{\lambda_1} \mathcal{B}_{\vec{p}_2}^{\lambda_2} \mathcal{B}_{\vec{p}_3}^{\lambda_3} \right\rangle'_{p_1 \ll p_2, p_3} = 24\sqrt{2} \left\langle \mathcal{B}_{\vec{p}_1}^{\lambda_1} \mathcal{B}_{-\vec{p}_1}^{\lambda_1} \right\rangle' \left\langle \mathcal{B}_{\vec{p}_2}^{\lambda_2} \mathcal{B}_{\vec{p}_3}^{\lambda_3} \right\rangle' \frac{1}{p_2^2} \mathcal{E}_1^{\lambda_1}(\vec{p}_1 | \vec{p}_2, \vec{p}_2). \quad (6.1)$$

At this stage we can use the argument that conformal symmetries fix the squeezed limit of the three-point correlator to match the one obtained in Ref. [33]. We have the freedom to normalise the spin-2 field as

$$\mathcal{B}_{ij} = \frac{1}{8\sqrt{2}} \gamma_{ij}, \quad (6.2)$$

where γ_{ij} is the graviton field. Its two-point correlator is

$$\langle \gamma_k^\lambda \gamma_{-\vec{k}}^{\lambda'} \rangle' = \frac{1}{128N} \frac{\delta^{\lambda\lambda'}}{k^3}, \quad (6.3)$$

and by choosing $N = M_{\text{p}}^2/128H^2$ one obtains the correct normalisation. We then obtain

$$\left\langle \gamma_{\vec{p}_1}^{\lambda_1} \gamma_{\vec{p}_2}^{\lambda_2} \gamma_{\vec{p}_3}^{\lambda_3} \right\rangle'_{\vec{p}_1 \ll \vec{p}_2, \vec{p}_3} = \frac{3}{p_1^3 p_2^3} \delta^{\lambda_2 \lambda_3} \epsilon_{i_1 i_2}^{* \lambda_1}(\vec{p}_1) \frac{p_2^{i_1} p_2^{i_2}}{p_2^2}, \quad (6.4)$$

which is the standard squeezed limit result [33] after accounting for notational differences. This does not come as a surprise. The tensor consistency relation in the squeezed limit is very robust and basically equivalent to the adiabaticity of the tensor perturbations on super-Hubble scales. Adiabaticity is a property of the long wavelength tensor modes in higher-spin gravity too as one can easily understand inspecting, for instance, the (Weyl)³ graviton interactions which depend only on time derivatives of the tensor fields. Therefore the tensor consistency relation is respected in higher-spin gravity. A confirmation of this result comes also from the scalar-scalar-graviton three-point function calculated in Ref. [26]

$$\langle \mathcal{B}_0(p_1) \mathcal{B}_0(p_2) \mathcal{B}_{2,ij}(p_3) \rangle = \frac{16\sqrt{2}}{N^2} \frac{1}{p_3^3} \frac{p_1 + p_2 + 2p_3}{(p_1 + p_2 + p_3)^2} \delta_{\vec{p}_1 + \vec{p}_2 + \vec{p}_3} \Pi_{ij,i'j'}(\vec{p}_3) p_1^{i'} p_2^{j'}. \quad (6.5)$$

By indicating with $\phi_{\vec{p}}$ the scalar with mass $2H^2$, the squeezed limit of such a three-point function reads

$$\left\langle \gamma_{\vec{p}_1}^\lambda \phi_{\vec{p}_2} \phi_{\vec{p}_3} \right\rangle'_{p_1 \ll p_2, p_3} = \left\langle \gamma_{\vec{p}_1}^{\lambda'} \gamma_{-\vec{p}_1}^{\lambda'} \right\rangle' \left\langle \phi_{\vec{p}_2} \phi_{\vec{p}_3} \right\rangle' \epsilon_{i_1 i_2}^{*\lambda}(\vec{p}_1) p_2^{i_1} p_2^{i_2}, \quad (6.6)$$

which is indeed the expected squeezed limit taking into account that the conformal weight of the scalar field is a conformal primary field of dimension $\Delta = 1$.

6.2 The equilateral limit

The equilateral limit $p \equiv p_1 = p_2 = p_3$ may be also immediately obtained by inserting in the expression (5.5) the coefficients (in A_5 we have removed the contact term)

$$A_1 = -\frac{1472\sqrt{2}}{3645N^2p^3}, \quad A_2 = -\frac{1664\sqrt{2}}{243N^2p}, \quad A_3 = \frac{3488\sqrt{2}p}{135N^2}, \quad A_4 = \frac{22592\sqrt{2}p}{405N^2}, \quad A_5 = -\frac{3152\sqrt{2}p^3}{405N^2}, \quad (6.7)$$

and evaluating the polarisation structures shown in Appendix G, in such a limit. The result is

$$\left\langle \gamma_{\vec{p}_1}^{\lambda_1} \gamma_{\vec{p}_2}^{\lambda_2} \gamma_{\vec{p}_3}^{\lambda_3} \right\rangle'_{p_1=p_2=p_3} = \frac{-3197 - 3044(\lambda_1\lambda_2 + \lambda_2\lambda_3 + \lambda_1\lambda_3)}{5184} \left(\left\langle \gamma_{\vec{p}}^{\lambda_1} \gamma_{-\vec{p}}^{\lambda_1} \right\rangle' \left\langle \gamma_{\vec{p}}^{\lambda_2} \gamma_{-\vec{p}}^{\lambda_2} \right\rangle' + \text{perm.} \right). \quad (6.8)$$

6.3 The generic shape

We can identify a few standard shapes for the graviton three-point correlators: the local one where the signal is dominated by squeezed configuration $p_1 \ll p_2 \simeq p_3$; the equilateral configuration whose signal is enhanced at the configuration $p_1 \simeq p_2 \simeq p_3$; the folded configuration whose signal is maximised at $p_1 + p_2 \simeq p_3$; and finally the orthogonal configuration ($p_1 \simeq p_2$) generating a signal with a positive enhancement at the equilateral configuration and a negative peak in the folded configuration. In Fig. 3 we plot the shape defined as

$$\mathcal{S}_{\lambda_1, \lambda_2, \lambda_3}(r_2, r_3) = \frac{\left\langle \gamma_{\vec{p}_1}^{\lambda_1} \gamma_{\vec{p}_2}^{\lambda_2} \gamma_{\vec{p}_3}^{\lambda_3} \right\rangle'}{\left\langle \gamma_{\vec{p}_1}^{\lambda_1} \gamma_{-\vec{p}_1}^{\lambda_1} \right\rangle' \left\langle \gamma_{\vec{p}_2}^{\lambda_2} \gamma_{-\vec{p}_2}^{\lambda_2} \right\rangle' + \text{perm.}}, \quad r_2 = \frac{p_2}{p_1} \quad \text{and} \quad r_3 = \frac{p_3}{p_1}, \quad (6.9)$$

for several combinations of the polarisations. The largest signal comes from the RRR combination (and therefore for the LLL combination) and is maximised for the equilateral configuration.

It is not clear what the observational prospects are for measuring the shapes of the tensor non-Gaussianities in the fortunate case that primordial gravitational waves from inflation are detected. At first sight, detecting tensor three-point correlators might look futuristic. A quadrupolar anisotropy in the tensor power spectrum can be induced by the non-Gaussian graviton three-point peaked in the squeezed limit. However, we have seen that higher-spin gravity does not lead to an enhancement of such an anisotropy with respect to the standard single-field model case. A study of the role played by the (Weyl)³ term in the CMB temperature intensity as well as the B-mode polarisation bispectra can be found in Ref. [57] from which one can preliminary estimate⁸ that a detection is possible if $L \gtrsim 10^{-5} M_p^{-1}$.

⁸We thank M. Shiraishi for discussions about this point.

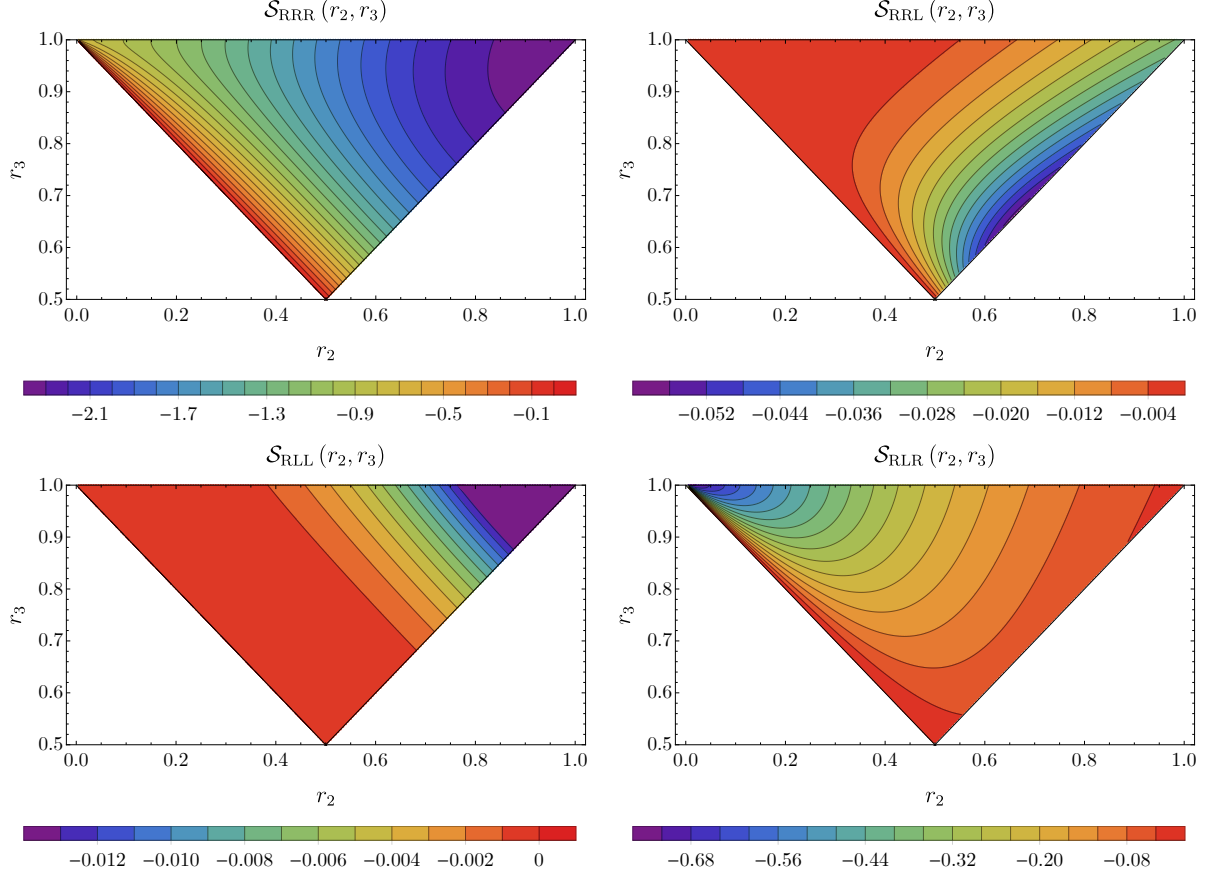


Figure 3. Shapes $\mathcal{S}_{\lambda_1, \lambda_2, \lambda_3}(r_2, r_3)$ for the independent combinations of the polarisations.

The first step towards characterising tensor non-Gaussianities with the Laser Interferometer Space Antenna (LISA) has been very recently taken in Ref. [58] (see also Refs. [59–61]) with determination of the interferometer three-point response functions. Even though a detailed study is not the scope of our paper, it would be certainly interesting to further investigate the detectability of the tensor non-Gaussianities from higher-spin gravity, with particular attention to the presence of the (Weyl)³-induced terms.

7 Conclusions

In this paper we have investigated non-Gaussian features of the graviton in the minimal Vasiliev theory. The theory contains an infinite tower of higher-spin fields for each even spin, and admits asymptotically de Sitter configurations. By exploiting the formalism of [26], we have calculated the exact three-point correlation function of the massless spin-2 field at late times. In accordance with symmetry arguments, we have shown that the shape of the graviton correlators is a linear combination of the shape produced by the standard Einstein term and the shape produced by a term cubic in the Weyl tensor. The Vasiliev model fixes the relative weight of these two pieces. We conclude with a few comments.

While we have considered the possibility of a higher-spin phase during inflation, we have not provided a mechanism to exit from the higher-spin phase into the current universe. Any such mechanism, as well as the physics responsible for the observed Gaussian scalar fluctuations, will go beyond the Vasiliev framework. It might be interesting to consider a curvaton-like scenario to generate the scalar fluctuations with the observed scalar tilt [62–64] whereby during the de Sitter

epoch the role of the curvaton might be played by some additional light scalar field. Perhaps the problem of Higgsing the higher-spin gauge symmetry [65, 66] down to the diffeomorphism group is relevant to these questions. We have also disregarded the correlators of higher-spin fields. The fate of such correlators is not clear (at least to us) once the universe has exited the de Sitter phase.⁹ On the other hand, since the graviton correlators we have computed are at super-Hubble wavelengths, they cannot be affected by local processes.

To provide evidence for our scenario, measuring the tensorial non-Gaussian shapes, and in particular those sourced by the cubic Weyl term, is of paramount importance. Interestingly, a considerable value for HL may provide evidence for additional degrees of freedom during inflation. In flat spacetime, higher-derivative cubic interactions of the massless graviton cause causality problems [68]. The introduction of an infinite tower of higher-spin states cures such a drawback. Even though it is not known that the causality problem persists in a de Sitter spacetime, it is reasonable to speculate that measuring a large higher-derivative graviton non-Gaussianity would indicate the presence of a tower of higher-spin states. Along this vein, it would be interesting to compare and contrast the predictions of higher-spin gravity to those of the weakly coupled holographic models put forward in Refs. [69, 70], or other models of Vasiliev gravity with de Sitter solutions [71–73], where the tensorial non-Gaussianities may also differ from those predicted by pure Einstein gravity.

As a final note, it is interesting to reflect on the picture painted in Ref. [74] (see also [69, 75–77]). There, it is imagined that cosmological evolution between the current de Sitter era and that during inflation should be viewed, holographically, as a renormalisation group flow between two fixed-points. The current de Sitter era corresponds to the ultraviolet fixed-point, and is strongly coupled. The inflationary era corresponds to the infrared fixed-point. If the infrared fixed point is moreover weakly coupled, it will contain an infinite tower of (almost) conserved currents. A bulk dual to a weakly coupled fixed point will contain a tower of light higher-spin particles [78–81]. Consequently, our scenario corresponds to a flow from strong to weak coupling. While such a flow is certainly allowed, the full space renormalisation group flows is sufficiently rich and varied to prevent us from deeming our scenario natural in the absence of experiment.

Acknowledgments

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A Polarisation and projection tensors

Polarisation tensors of higher-spin fields can be obtained generalising the notion of polarisation vectors introducing positive and negative energy wave functions [20]

$$\begin{aligned}\epsilon_{i_1 \dots i_s}^{\lambda}(\vec{k}) &= \sum_{\lambda_1, \dots, \lambda_s = \pm 1} \delta_{\lambda_1 + \dots + \lambda_s, \lambda} \sqrt{\frac{2^s (s + \lambda)! (s - \lambda)!}{(2s)! \prod_{i=1}^s (1 + \lambda_i)! (1 - \lambda_i)!}} \prod_{j=1}^s \epsilon_{i_j}^{\lambda_j}(\vec{k}), \\ \epsilon_{i_1 \dots i_s}^{*\lambda}(\vec{k}) &= \sum_{\lambda_1, \dots, \lambda_s = \pm 1} \delta_{\lambda_1 + \dots + \lambda_s, \lambda} \sqrt{\frac{2^s (s + \lambda)! (s - \lambda)!}{(2s)! \prod_{i=1}^s (1 + \lambda_i)! (1 - \lambda_i)!}} \prod_{j=1}^s \epsilon_{i_j}^{*\lambda_j}(\vec{k}),\end{aligned}\quad (\text{A.1})$$

⁹FRW-like solutions for higher-spin gravity have been constructed in Ref. [67].

where ϵ_i^λ and $\epsilon_i^{*\lambda}$ are positive and negative energy wave functions for a spin-one field, with

$$\epsilon_i^{*\lambda} = (-1)^\lambda \epsilon_i^{-\lambda}. \quad (\text{A.2})$$

It is useful to define the projector tensor in d -dimensions as

$$\Pi_{i_1 \dots i_s, j_1 \dots j_s}(\vec{k}) \equiv \sum_{\lambda} \epsilon_{i_1 \dots i_s}^{\lambda}(\vec{k}) \epsilon_{j_1 \dots j_s}^{*\lambda}(\vec{k}). \quad (\text{A.3})$$

For instance, for spin-2 in three-dimensions we obtain (summing only over the maximally transverse modes as lower helicity states are zero in the transverse traceless gauge)

$$\Pi_{i_1 i_2, j_1 j_2}(\vec{k}) = \frac{1}{2} \left(\Pi_{i_1, j_1}(\vec{k}) \Pi_{i_2, j_2}(\vec{k}) + \Pi_{i_1, j_2}(\vec{k}) \Pi_{i_2, j_1}(\vec{k}) \right) - \frac{1}{2} \Pi_{i_1, i_2}(\vec{k}) \Pi_{j_1, j_2}(\vec{k}). \quad (\text{A.4})$$

Written explicitly in terms of the expanded spin-one projector $\Pi_{i,j}(\vec{k}) = \delta_{ij} - \hat{k}_i \hat{k}_j$, one gets

$$\begin{aligned} \Pi_{i_1 i_2, j_1 j_2}(\vec{k}) = \frac{1}{2} \Big[& (\delta_{i_1 j_1} \delta_{i_2 j_2} + \delta_{i_1 j_2} \delta_{i_2 j_1} - \delta_{i_1 i_2} \delta_{j_1 j_2}) + \hat{k}_{i_1} \hat{k}_{i_2} \hat{k}_{j_1} \hat{k}_{j_2} - \left(\delta_{i_1 j_1} \hat{k}_{i_2} \hat{k}_{j_2} \right. \\ & \left. + \delta_{i_1 j_2} \hat{k}_{i_2} \hat{k}_{j_1} + \delta_{i_2 j_1} \hat{k}_{i_1} \hat{k}_{j_2} + \delta_{i_2 j_2} \hat{k}_{i_1} \hat{k}_{j_1} - \delta_{i_1 i_2} \hat{k}_{j_1} \hat{k}_{j_2} - \delta_{j_1 j_2} \hat{k}_{i_1} \hat{k}_{i_2} \right) \Big]. \end{aligned} \quad (\text{A.5})$$

B Shadow transform

The shadow transform can be defined as follows. From a primary field $O_{s,\Delta}(\vec{x})$ of spin- s and scaling dimension Δ under the d -dimensional Euclidean conformal group $\text{SO}(1, d+1)$, we can construct a dual primary field

$$\tilde{O}_{s,\tilde{\Delta}}(\vec{x}) = \int d^d y G_{s,\tilde{\Delta}}(\vec{x} - \vec{y}) O_{s,\Delta}(\vec{y}), \quad (\text{B.1})$$

named shadow transform of $O_{s,\Delta}$, characterised by the same spin- s and conjugate scaling dimension

$$\tilde{\Delta} = d - \Delta. \quad (\text{B.2})$$

The kernel of the transformation $G_{s,\tilde{\Delta}}(\vec{x} - \vec{y})$ is represented by the two-point function of spin- s , dimension $\tilde{\Delta}$ operators in a d -dimensional conformal field theory. For example, the shadow transform of a scalar field O is

$$\tilde{O}_{\tilde{\Delta}}(\vec{x}) = \int d^d y \frac{c_{\tilde{\Delta}}}{|\vec{x} - \vec{y}|^{2\tilde{\Delta}}} O_{\Delta}(\vec{y}) \quad (\text{B.3})$$

where $c_{\tilde{\Delta}}$ is a constant normalisation factor. Such a kernel makes the operator $\tilde{O}_{\tilde{\Delta}}(\vec{x})$ transform as a local primary field of dimension $\tilde{\Delta}$ under the conformal group. It is also clear that the inverse of a shadow transform is again a shadow transform.

In momentum space, the shadow transform is simply obtained by Fourier transforming the real space result. For higher-spin fields, this procedure is more complicated due to the presence of tensor operators; however, as outlined in Ref. [26], it is still possible to shadow relate the dual boundary fields $B_s(k)$ of conformal weight $\tilde{\Delta} = s+1$ and the local ones $\mathcal{B}_s(k)$ of conformal weight $\Delta = 2 - s$ as

$$B_s^{i_1 \dots i_s}(k) = G_{s,\tilde{\Delta}=s+1}^{i_1 \dots i_s, m_1 \dots m_s}(\vec{k}, \vec{k}') \mathcal{B}_{s, m_1 \dots m_s}(k'), \quad (\text{B.4})$$

where the Fourier transform of the shadow kernel is given, in the $d \rightarrow 3$ limit and for $s \geq 1$, by

$$G_{s,\tilde{\Delta}=s+1}^{i_1 \dots i_s, m_1 \dots m_s}(\vec{k}, \vec{k}') = \frac{(-1)^s \pi^2}{(2s)!} c_{s,\tilde{\Delta}=s+1} k^{2s-1} \Pi^{i_1 \dots i_s, m_1 \dots m_s}(\vec{k}) \delta_{\vec{k}+\vec{k}'}, \quad (\text{B.5})$$

where $\Pi_{i_1 \dots i_s, m_1 \dots m_s}(\vec{k})$ is the projector presented previously in Appendix A. For example, the shadow transformation rules for the spin-0 and spin-2 boundary fields is shown to be

$$B_0(p) = \frac{1}{p} \mathcal{B}_0(p), \quad B_{ij}(p) = p^3 \Pi^{i' j'}_{,ij}(\vec{p}) \mathcal{B}_{2, i' j'}(p). \quad (\text{B.6})$$

C Double-K integrals

In this appendix we show how to treat integrals of the form

$$\mathcal{I}_0^{ijlm} = \int \frac{d^d \vec{k}}{(2\pi)^d} \frac{1}{|\vec{k}|^{2\delta_1}} \frac{1}{|\vec{k} - \vec{p}_1|^{2\delta_2}} \left(k^i k^j k^l k^m \right), \quad (\text{C.1})$$

which we refer to as “double-K integrals”. Integrals of this type enter in the computation of the graviton 2-point function. Using the known Schwinger parametrization

$$\frac{1}{A^\alpha} = \frac{1}{\Gamma(\alpha)} \int_0^\infty ds s^{\alpha-1} e^{-sA}, \quad (\text{C.2})$$

with $\alpha > 0$, we find

$$\mathcal{I}_0^{ijlm} = \int \frac{d^d k}{(2\pi)^d} k^i k^j k^l k^m \int_{\mathbb{R}_+^2} ds_1 ds_2 \frac{s_1^{\delta_1-1}}{\Gamma(\delta_1)} \frac{s_2^{\delta_2-1}}{\Gamma(\delta_2)} e^{-(s_1 |\vec{k}|^2 + s_2 |\vec{k} - \vec{p}_1|^2)}. \quad (\text{C.3})$$

Next, we set $s_t = s_1 + s_2$, $\vec{l} = \vec{k} - \frac{s_2}{s_1+s_2} \vec{p}_1$ and $\Delta = \frac{s_1 s_2}{s_t} p_1^2$, such that the integral can be written as

$$\int_{\mathbb{R}_+^2} ds_1 ds_2 \frac{s_1^{\delta_1-1}}{\Gamma(\delta_1)} \frac{s_2^{\delta_2-1}}{\Gamma(\delta_2)} e^{-\Delta} \int \frac{d^d l}{(2\pi)^d} e^{-s_t l^2} \left[\left(l + \frac{s_2}{s_1+s_2} p_1 \right)^i \cdots \left(l + \frac{s_2}{s_1+s_2} p_1 \right)^m \right]. \quad (\text{C.4})$$

This expression can be expanded and split up into a sum of integrals. For any a such that $a > 0$, the integral over l can be performed as follows

$$\int \frac{d^d \vec{l}}{(2\pi)^d} l^{2n} e^{-al^2} = \frac{\Gamma(\frac{d}{2} + n)}{(4\pi)^{\frac{d}{2}} \Gamma(\frac{d}{2})} \frac{1}{a^{\frac{d}{2} + n}}, \quad (\text{C.5})$$

$$\int \frac{d^d \vec{l}}{(2\pi)^d} l^{i_1} \dots l^{i_{2n}} e^{-al^2} = \frac{S^{i_1 \dots i_{2n}}}{(4\pi)^{\frac{d}{2}} 2^n a^{\frac{d}{2} + n}}, \quad (\text{C.6})$$

while the presence of an odd number of l makes the integrals vanish. We also defined $S^{i_1 \dots i_{2m}}$ to be a completely symmetric tensor with unitary coefficients as, for example,

$$\begin{aligned} S^{i_1 i_2} &= \delta^{i_1 i_2}, \\ S^{i_1 i_2 i_3 i_4} &= \delta^{i_1 i_2} \delta^{i_3 i_4} + \delta^{i_1 i_3} \delta^{i_2 i_4} + \delta^{i_1 i_4} \delta^{i_2 i_3}, \\ S^{i_1 i_2 i_3 i_4 i_5 i_6} &= \delta^{i_1 i_2} \delta^{i_3 i_4} \delta^{i_5 i_6} + \delta^{i_1 i_2} \delta^{i_3 i_5} \delta^{i_4 i_6} + \delta^{i_1 i_2} \delta^{i_3 i_6} \delta^{i_4 i_5} + \delta^{i_1 i_3} \delta^{i_2 i_4} \delta^{i_5 i_6} \\ &\quad + \delta^{i_1 i_3} \delta^{i_2 i_5} \delta^{i_4 i_6} + \delta^{i_1 i_3} \delta^{i_2 i_6} \delta^{i_4 i_5} + \delta^{i_1 i_4} \delta^{i_2 i_3} \delta^{i_5 i_6} + \delta^{i_1 i_4} \delta^{i_2 i_5} \delta^{i_3 i_6} \\ &\quad + \delta^{i_1 i_4} \delta^{i_2 i_6} \delta^{i_3 i_5} + \delta^{i_1 i_5} \delta^{i_2 i_3} \delta^{i_4 i_6} + \delta^{i_1 i_5} \delta^{i_2 i_4} \delta^{i_3 i_6} + \delta^{i_1 i_5} \delta^{i_2 i_6} \delta^{i_3 i_4} \\ &\quad + \delta^{i_1 i_6} \delta^{i_2 i_3} \delta^{i_4 i_5} + \delta^{i_1 i_6} \delta^{i_2 i_4} \delta^{i_3 i_5} + \delta^{i_1 i_6} \delta^{i_2 i_5} \delta^{i_3 i_4}. \end{aligned} \quad (\text{C.7})$$

Of all these pieces in the l integral, let us focus on the one containing $l^i l^j l^l l^m$ in the numerator, since it is the one proportional to the Dirac deltas. This is the one which is relevant for our computations, the others can be computed accordingly. Thus, we find

$$\int_{\mathbb{R}_+^2} ds_1 ds_2 \frac{s_1^{\delta_1-1} s_2^{\delta_2-1}}{\Gamma^2} e^{-\Delta} \int \frac{d^d l}{(2\pi)^d} e^{-s_t l^2} l^i l^j l^l l^m = \frac{S^{ijklm}}{4 (4\pi)^{\frac{d}{2}} \Gamma^2} \int_{\mathbb{R}_+^2} ds_1 ds_2 s_1^{\delta_1-1} s_2^{\delta_2-1} s_t^{-(\frac{d}{2}+2)} e^{-\Delta}, \quad (\text{C.8})$$

where $\Gamma^2 = \Gamma(\delta_1) \Gamma(\delta_2)$. We can change the variables s_1, s_2 to v_1 and v_2 as

$$s_1 = \frac{(v_1 + v_2)^2}{2v_1} = \frac{V}{2v_1}, \quad s_2 = \frac{(v_1 + v_2)^2}{2v_2} = \frac{V}{2v_2}, \quad s_t = \frac{(v_1 + v_2)^3}{2v_1 v_2} = \frac{V^{3/2}}{2v_1 v_2}. \quad (\text{C.9})$$

The determinant of the Jacobian of the transformation is given by

$$\det |J| = \left| -\frac{(v_1 + v_2)^4}{4v_1^2 v_2^2} \right| = \frac{V^2}{4v_1^2 v_2^2}, \quad (\text{C.10})$$

such that the integral becomes

$$\mathcal{I}_0^{ijlm} \supset \frac{S^{ijlm}}{(4\pi)^{\frac{d}{2}} 2^{-\frac{d}{2} + \delta_1 + \delta_2} \Gamma(\delta_1) \Gamma(\delta_2)} \int_{\mathbb{R}_+^2} dv_1 dv_2 (v_1 + v_2)^{2(\delta_1 + \delta_2 - 3\frac{d}{4} - 3)} v_1^{\frac{d}{2} - \delta_1 + 1} v_2^{\frac{d}{2} - \delta_2 + 1} e^{-\left(\frac{v_1 + v_2}{2}\right) p_1^2}. \quad (\text{C.11})$$

We introduce a new Schwinger parameter with $\alpha = 3d/2 + 6 - 2\delta_t$ and $A = (v_1 + v_2) / (v_1 v_2)$, so that

$$\mathcal{I}_0^{ijlm} \supset \frac{2^{\frac{d}{2} - \delta_t} S^{ijlm}}{(4\pi)^{\frac{d}{2}} \Gamma(\delta_1) \Gamma(\delta_2) \Gamma\left(\frac{3d}{2} + 6 - 2\delta_t\right)} \int_{\mathbb{R}_+^2} dv_1 dv_2 \int_0^\infty dt t^{\frac{3d}{2} + 5 - 2\delta_t} \prod_{j=1}^2 e^{-\frac{t}{v_j}} e^{-\frac{v_j}{2} p_j^2} v_j^{-d + 2\delta_t - \delta_j - 5}. \quad (\text{C.12})$$

Now we perform the change of variables $u_i = p_i^2 v_i / 2$ and by using the definition of the Bessel functions

$$K_j(z) = \frac{1}{2} \left(\frac{z}{2}\right)^j \int_0^\infty e^{-u - \frac{z^2}{4u}} u^{-j-1} du, \quad |\arg z| < \frac{\pi}{4}, \quad (\text{C.13})$$

we can rewrite the integral as

$$\begin{aligned} \mathcal{I}_0^{ijlm} \supset & \frac{2^{-\frac{3d}{2} + 2\delta_t - 8} S^{ijlm}}{(4\pi)^{\frac{d}{2}} \Gamma(\delta_1) \Gamma(\delta_2) \Gamma\left(\frac{3d}{2} + 6 - 2\delta_t\right) 2^{-5 + \delta_t - \frac{1}{2}d}} \int_0^\infty dt \left(\sqrt{2t}\right)^{d+2-\delta_t} \\ & \times \prod_{i=1}^2 p_i^{d-2\delta_t + \delta_i + 4} K_{d-2\delta_t + \delta_i + 4}(\sqrt{2t} p_i), \end{aligned} \quad (\text{C.14})$$

where we introduced an additional vector $\vec{p}_2 = -\vec{p}_1$ as usual in the 2-point function. We redefine now the integration variable $x = \sqrt{2t}$ and get

$$\mathcal{I}_0^{ijlm} \supset \frac{2^{-d + \delta_t - 3} S^{ijlm}}{(4\pi)^{\frac{d}{2}} \Gamma(\delta_1) \Gamma(\delta_2) \Gamma\left(\frac{3d}{2} + 6 - 2\delta_t\right)} \int_0^\infty dx x^{d+3-\delta_t} \prod_{i=1}^2 p_i^{d-2\delta_t + \delta_i + 4} K_{d-2\delta_t + \delta_i + 4}(x p_i). \quad (\text{C.15})$$

Finally, defining the double-K integral as

$$I_{\alpha\{\beta_1, \beta_2\}}(p_1, p_2) = \int_0^\infty dx x^\alpha \prod_{j=1}^2 p_j^{\beta_j} K_{\beta_j}(p_j x), \quad (\text{C.16})$$

we can write

$$\mathcal{I}_0^{ijlm} \supset \frac{2^{-d + \delta_t - 3} S^{ijlm}}{(4\pi)^{\frac{d}{2}} \Gamma(\delta_1) \Gamma(\delta_2) \Gamma\left(\frac{3d}{2} + 6 - 2\delta_t\right)} I_{d+3-\delta_t\{d-2\delta_t + \delta_1 + 4, d-2\delta_t + \delta_2 + 4\}}(p_1, p_2). \quad (\text{C.17})$$

D Triple-K integrals

In the computation of three-point functions like that of Eq. (4.6) we could incur in momentum space integrals of the form

$$\mathcal{I}_{r, p_1 p_2}^{i_1 \dots i_r} = \int \frac{d^d \vec{k}}{(2\pi)^d} \frac{k^{i_1} \dots k^{i_r}}{|\vec{k}|^{2\delta_3} |\vec{k} - \vec{p}_1|^{2\delta_2} |\vec{k} + \vec{p}_2|^{2\delta_1}}, \quad (\text{D.1})$$

where $\vec{p}_1, \vec{p}_2, \vec{p}_3$ identify three external momenta satisfying the condition $\vec{p}_1 + \vec{p}_2 + \vec{p}_3 = 0$. To solve such an integral we will follow the procedure outlined in Appendix A.3 of Ref. [48]. Using the Schwinger parametrization defined in Eq. (C.2) we can write the previous integral as

$$\mathcal{I}_{r,p_1 p_2}^{i_1 \dots i_r} = \int \frac{d^d \vec{k}}{(2\pi)^d} k^{i_1} \dots k^{i_r} \int_{\mathbb{R}_+^3} d\vec{s} \frac{s_1^{\delta_1-1}}{\Gamma(\delta_1)} \frac{s_2^{\delta_2-1}}{\Gamma(\delta_2)} \frac{s_3^{\delta_3-1}}{\Gamma(\delta_3)} e^{-(s_3|\vec{k}|^2 + s_2|\vec{k}-\vec{p}_1|^2 + s_1|\vec{k}+\vec{p}_2|^2)}, \quad (\text{D.2})$$

where $d\vec{s} = ds_1 ds_2 ds_3$ and $\Gamma^3 = \Gamma(\delta_1)\Gamma(\delta_2)\Gamma(\delta_3)$. Then we can set $s_t = s_1 + s_2 + s_3$, $\vec{l} = \vec{k} + \frac{s_1 \vec{p}_2 - s_2 \vec{p}_1}{s_t}$ and $\Delta = \frac{s_1 s_2 p_3^2 + s_1 s_3 p_2^2 + s_2 s_3 p_1^2}{s_t}$, such that $s_3|\vec{k}|^2 + s_2|\vec{k}-\vec{p}_1|^2 + s_1|\vec{k}+\vec{p}_2|^2 = s_t l^2 + \Delta$. The integral in Eq. (D.1) then acquires the form

$$\mathcal{I}_{r,p_1 p_2}^{i_1 \dots i_r} = \Gamma^{-3} \int_{\mathbb{R}_+^3} d\vec{s} s_1^{\delta_1-1} s_2^{\delta_2-1} s_3^{\delta_3-1} e^{-\Delta} \int \frac{d^d \vec{l}}{(2\pi)^d} e^{-s_t l^2} \prod_{j=1}^r \left(l^{i_j} + \frac{s_2 p_1^{i_j} - s_1 p_2^{i_j}}{s_t} \right). \quad (\text{D.3})$$

This expression can be expanded and the integral in l can be computed using Eq. (C.5). The result can be split up into a sum of integrals of the form

$$i_{d,m,\{\delta_j\}} = \frac{1}{(4\pi)^{\frac{d}{2}} 2^m \Gamma^3} \int_{\mathbb{R}_+^3} d\vec{s} s_t^{-\frac{d}{2}-m} s_1^{\delta_1-1} s_2^{\delta_2-1} s_3^{\delta_3-1} e^{-\Delta}. \quad (\text{D.4})$$

Be careful that the parameters δ_i are not necessarily the ones present in Eq. (D.1) because additional powers of s_i can appear from the numerator product. On the other hand, the numerical value of Γ^3 is left unchanged. Similarly to the computation performed in the previous section, we recast Eq. (D.4) as:

$$\begin{aligned} i_{d,m,\{\delta_j\}} &= \frac{2^{-\frac{d}{2}-2m+4}}{(4\pi)^{\frac{d}{2}} \Gamma^3 \Gamma(d+2m-\delta_t)} \int_0^\infty dx x^{\frac{d}{2}+m-1} \prod_{j=1}^3 p_j^{\frac{d}{2}+m-\delta_t+\delta_j} K_{\frac{d}{2}+m-\delta_t+\delta_j}(p_j x) \\ &= \frac{2^{-\frac{d}{2}-2m+4}}{(4\pi)^{\frac{d}{2}} \Gamma^3 \Gamma(d+2m-\delta_t)} I_{\frac{d}{2}+m-1\{\frac{d}{2}+m-\delta_t+\delta_j\}}, \end{aligned} \quad (\text{D.5})$$

where $\delta_t = \delta_1 + \delta_2 + \delta_3$. Finally, we isolated the structure of the triple-K integral

$$I_{\alpha\{\beta_1, \beta_2, \beta_3\}}(p_1, p_2, p_3) = \int_0^\infty dx x^\alpha \prod_{j=1}^3 p_j^{\beta_j} K_{\beta_j}(p_j x), \quad (\text{D.6})$$

which is going to be the building block for the solution of the considered integrals. Using the Bessel-K function identities

$$\begin{aligned} \frac{\partial}{\partial a} [a^\nu K_\nu(ax)] &= -x a^\nu K_{\nu-1}(ax), \\ K_{\nu-1}(x) + \frac{2j}{x} K_\nu(x) &= K_{\nu+1}(x), \\ K_{-\nu}(x) &= K_\nu(x), \end{aligned} \quad (\text{D.7})$$

we find the following relations involving triple-K integrals

$$\frac{\partial}{\partial p_n} I_{\alpha\{\beta_j\}} = -p_n I_{\alpha+1\{\beta_j-\delta_{jn}\}}, \quad (\text{D.8})$$

$$I_{\alpha\{\beta_j+\delta_{jn}\}} = p_n^2 I_{\alpha\{\beta_j-\delta_{jn}\}} + 2\beta_n I_{\alpha-1\{\beta_j\}}, \quad (\text{D.9})$$

$$I_{\alpha\{\beta_1 \beta_2, -\beta_3\}} = p_3^{-2\beta_3} I_{\alpha\{\beta_1 \beta_2 \beta_3\}}, \quad (\text{D.10})$$

for any $n = 1, 2, 3$. One can also arrange them to get the iterative formula

$$I_{\alpha+1\{\beta_j+\delta_{jn}\}} = -p_n \frac{\partial}{\partial p_n} I_{\alpha\{\beta_j\}} + 2\beta_n I_{\alpha\{\beta_j\}}. \quad (\text{D.11})$$

One is typically able to handle these expressions in terms of simple polynomials of the external momenta, apart from when they are divergent and need to be regularised. This task is described in detail in the following appendix.

D.1 Recursive formula

Our computation involves many different integrals of the kind shown in (D.1) and it is, therefore, useful to write down their relation to the triple-K integrals in terms of recursive formulas. In this section we are going to specialise the result to the case where δ_i defining the integral in Eq. (D.1) are equal to 1. The structure of the integrals comes from the following product, see Eq. (D.3)

$$\mathcal{I}_{r,p_1 p_2}^{i_1 \dots i_r} = \int_{\mathbb{R}_+^3} d\vec{s} s_1^{\delta_1-1} s_2^{\delta_2-1} s_3^{\delta_3-1} e^{-\Delta} \int \frac{d^d \vec{l}}{(2\pi)^d} e^{-s_t l^2} \left[\left(l + \frac{s_2 p_1 - s_1 p_2}{s_t} \right)^{i_1} \dots \left(l + \frac{s_2 p_1 - s_1 p_2}{s_t} \right)^{i_r} \right]. \quad (\text{D.12})$$

The solution can be written in terms of a recursive formula, once the expression of the polynomial $\prod_n (l + (s_2 p_1 - s_1 p_2)/s_t)^{i_n}$ has been expanded, as

$$\mathcal{I}_{r,p_1 p_2}^{i_1 \dots i_r} = \sum_{\text{all terms}} \left[(-1)^{n_{p_2} 2^{n_{p_1} + n_{p_2}}} \left(i_3, \frac{n_l}{2} + n_{p_1} + n_{p_2}, \{1 + n_{p_2}, 1 + n_{p_1}, 1\} \right) p_1^{i_1 \dots i_{n_{p_1}}} p_2^{i_{n_{p_1}+1} \dots i_{n_{p_1} + n_{p_2}}} \right], \quad (\text{D.13})$$

where n_l and n_{p_i} stand for the number of l and p_i , respectively, in the numerator of the considered piece. Notice that they manifest an explicit symmetry under the exchange of p_1 and p_2 . The integrals with cyclic permutations of p_i are exactly the same once one has swapped the positions of the indices in $i_{d,m,\{\delta_i\}}$ accordingly. Thus we find

$$\begin{aligned} \mathcal{I}_{r,p_3 p_1}^{i_1 \dots i_r} &= \sum_{\text{all terms}} \left[(-1)^{n_{p_1} 2^{n_{p_3} + n_{p_1}}} \left(i_3, \frac{n_l}{2} + n_{p_3} + n_{p_1}, \{1 + n_{p_3}, 1, 1 + n_{p_1}\} \right) p_3^{i_1 \dots i_{n_{p_3}}} p_1^{i_{n_{p_3}+1} \dots i_{n_{p_3} + n_{p_1}}} \right], \\ \mathcal{I}_{r,p_2 p_3}^{i_1 \dots i_r} &= \sum_{\text{all terms}} \left[(-1)^{n_{p_3} 2^{n_{p_2} + n_{p_3}}} \left(i_3, \frac{n_l}{2} + n_{p_2} + n_{p_3}, \{1, 1 + n_{p_3}, 1 + n_{p_2}\} \right) p_2^{i_1 \dots i_{n_{p_2}}} p_3^{i_{n_{p_2}+1} \dots i_{n_{p_2} + n_{p_3}}} \right]. \end{aligned} \quad (\text{D.14})$$

In the following we provide some examples of integrals involving the external momenta \vec{p}_1 and \vec{p}_2 found by using the previous recursive formula. The others can easily be found by using the symmetry under cyclic permutations of the momenta.

- Integral $\mathcal{I}_{0,p_1 p_2}$:

$$\mathcal{I}_{0,p_1 p_2} = \int_k \frac{1}{\vec{k}^2 |\vec{k} - \vec{p}_1|^2 |\vec{k} + \vec{p}_2|^2} = i_{3,0,\{1,1,1\}} = \frac{1}{8p_1 p_2 p_3}. \quad (\text{D.15})$$

- Integral $\mathcal{I}_{1,p_1 p_2}^{i_1}$:

$$\mathcal{I}_{1,p_1 p_2}^{i_1} = \int_k \frac{k^{i_1}}{\vec{k}^2 |\vec{k} - \vec{p}_1|^2 |\vec{k} + \vec{p}_2|^2} = 2p_1^{i_1} i_{3,1,\{1,2,1\}} - 2p_2^{i_1} i_{3,1,\{2,1,1\}}. \quad (\text{D.16})$$

- Integral $\mathcal{I}_{2,p_1 p_2}^{i_1 i_2}$:

$$\begin{aligned} \mathcal{I}_{2,p_1 p_2}^{i_1 i_2} &= \int_k \frac{k^{i_1} k^{i_2}}{\vec{k}^2 |\vec{k} - \vec{p}_1|^2 |\vec{k} + \vec{p}_2|^2} = \delta^{i_1 i_2} i_{3,1,\{1,1,1\}} + 4p_1^{i_1} p_1^{i_2} i_{3,2,\{1,3,1\}} \\ &\quad - 4p_1^{i_1} p_2^{i_2} i_{3,2,\{2,2,1\}} - 4p_2^{i_1} p_1^{i_2} i_{3,2,\{2,2,1\}} + 4p_2^{i_1} p_2^{i_2} i_{3,2,\{3,1,1\}}. \end{aligned} \quad (\text{D.17})$$

The integrals \mathcal{I}_3 , \mathcal{I}_4 , \mathcal{I}_5 , \mathcal{I}_6 can be found in the same way and contain 14, 41, 122, and 365 terms respectively. Furthermore, \mathcal{I}_4 , \mathcal{I}_5 , \mathcal{I}_6 contain divergent terms which need to be regularised. The procedure is outlined in Appendix E. The convergent ones were also checked numerically.

E Regularisation

In many of the computations performed, one arrives to expressions involving integrals of Bessel-K functions which could be divergent. In the following we provide the regularisation procedure focusing on the triple-K case since the simpler double-K strictly follows from analogous considerations. In the later subsections, we are going to focus on each case separately.

In the computation of the correlators we encounter triple-K integrals of the form

$$I_{\alpha\{\beta_1,\beta_2,\beta_3\}}(p_1,p_2,p_3) = \int_0^\infty dx x^\alpha \prod_{j=1}^3 p_j^{\beta_j} K_{\beta_j}(p_j x). \quad (\text{E.1})$$

The integral depends only on four parameters (α, β_j) , since p_j are the external momenta. The integral is always convergent at large values of x due to the properties of the Bessel functions, while a divergence can come from the singularity at the lower limit $x = 0$. In particular, the integral converges if the following condition holds

$$\alpha > \sum_{j=1}^3 |\beta_j| - 1. \quad (\text{E.2})$$

Recall that we use p_j to denote the modulus of the vectors \vec{p}_j and therefore is always positive by construction. In case the condition is not satisfied by the parameters, the integral is divergent and needs to be regularised. The regularisation procedure was laid down in Ref. [48] and it is based on analytic continuation. We sum up the main steps here. One can introduce two additional real parameters u and v such that

$$I_{\alpha\{\beta_1,\beta_2,\beta_3\}} \rightarrow I_{\alpha+u\epsilon\{\beta_1+v\epsilon,\beta_2+v\epsilon,\beta_3+v\epsilon\}}. \quad (\text{E.3})$$

The original integral is recovered in the limit of $\epsilon \rightarrow 0$. The limit exists and the analytically continued integral is independent of the choice of u and v except when one of the following conditions is met

$$\alpha + 1 \pm \beta_1 \pm \beta_2 \pm \beta_3 = -2n, \quad (\text{E.4})$$

where n is a non-negative integer. In these cases the solution contains a pole of the form $1/\epsilon$ and a dependence on u and v is still present. For example, one can perform the dimensional regularisation using $u = v = -1/2$ since

$$d \rightarrow d + 2u\epsilon, \quad \Delta_j \rightarrow \Delta_j + (u + v)\epsilon. \quad (\text{E.5})$$

E.1 Double-K integrals

The general solution of the double-K integral is

$$\begin{aligned} I_{\alpha\{\beta_1,\beta_2\}}(p,p) &= p^{\beta_1+\beta_2} \int_0^\infty dx x^\alpha K_{\beta_1}(px) K_{\beta_2}(px) = \frac{2^{\alpha-2}}{\Gamma(\alpha+1)p^{\alpha+1-\beta_1-\beta_2}} \\ &\times \Gamma\left(\frac{\alpha+\beta_1+\beta_2+1}{2}\right) \Gamma\left(\frac{\alpha+\beta_1-\beta_2+1}{2}\right) \Gamma\left(\frac{\alpha-\beta_1+\beta_2+1}{2}\right) \Gamma\left(\frac{\alpha-\beta_1-\beta_2+1}{2}\right), \end{aligned} \quad (\text{E.6})$$

valid for

$$\operatorname{Re}(\alpha + 1) > |\operatorname{Re} \beta_1| + |\operatorname{Re} \beta_2|. \quad (\text{E.7})$$

Thanks to the regularisation procedure

$$I_{\alpha\{\beta_1, \beta_2\}} \rightarrow I_{\alpha+u\epsilon\{\beta_1+v\epsilon, \beta_2+v\epsilon\}}, \quad (\text{E.8})$$

the preceding formula can also be used in the divergent cases and the result can be analytically continued by performing the limit $\epsilon \rightarrow 0$, after the eventual pole in ϵ is isolated. For example

$$I_{4, \{4, 4\}}(p, p) = \frac{10395\pi^2}{512} p^3. \quad (\text{E.9})$$

E.2 Triple-K integrals

The general solution of the triple-K integral is known to be

$$\begin{aligned} I_{\alpha\{\beta_1, \beta_2, \beta_3\}}(p_1, p_2, p_3) &= p_1^{\beta_1} p_2^{\beta_2} p_3^{\beta_3} \int_0^\infty dx x^\alpha K_{\beta_1}(p_1 x) K_{\beta_2}(p_2 x) K_{\beta_3}(p_3 x) \\ &= p_1^{\beta_1} p_2^{\beta_2} p_3^{\beta_3} \frac{2^{\alpha-3}}{p_3^{\alpha+1}} [A(\beta_1, \beta_2) + A(\beta_1, -\beta_2) + A(-\beta_1, \beta_2) + A(-\beta_1, -\beta_2)], \end{aligned} \quad (\text{E.10})$$

where

$$\begin{aligned} A(\beta_1, \beta_2) &= \left(\frac{p_1}{p_3}\right)^{\beta_1} \left(\frac{p_2}{p_3}\right)^{\beta_2} \Gamma\left(\frac{\alpha + \beta_1 + \beta_2 - \beta_3 + 1}{2}\right) \Gamma\left(\frac{\alpha + \beta_1 + \beta_2 + \beta_3 + 1}{2}\right) \Gamma(-\beta_1) \Gamma(-\beta_2) \\ &\times F_4\left(\frac{\alpha + \beta_1 + \beta_2 - \beta_3 + 1}{2}, \frac{\alpha + \beta_1 + \beta_2 + \beta_3 + 1}{2}; \beta_1 + 1, \beta_2 + 1; \frac{p_1^2}{p_3^2}, \frac{p_2^2}{p_3^2}\right), \end{aligned} \quad (\text{E.11})$$

valid for

$$\operatorname{Re}(\alpha + 1) > |\operatorname{Re} \beta_1| + |\operatorname{Re} \beta_2| + |\operatorname{Re} \beta_3|. \quad (\text{E.12})$$

The analytical continuation allows to use the preceding formula in the cases where the condition in Eq. (E.12) is not met. Once the eventual pole in ϵ is factorised, the limit $\epsilon \rightarrow 0$ can be found. Some examples of regularised integrals appearing in our computations are the following (see Refs. [48, 50])

$$\begin{aligned} I_{\frac{5}{2}+\epsilon\{\frac{3}{2}\frac{3}{2}\frac{3}{2}\}} &= -\left(\frac{\pi}{2}\right)^{3/2} \frac{1}{(p_1 + p_2 + p_3)^2} [2p_1 p_2 p_3 + p_1^3 + p_2^3 + p_3^3 \\ &\quad + 2(p_1^2 p_2 + p_1 p_2^2 + p_1^2 p_3 + p_1 p_3^2 + p_2^2 p_3 + p_2 p_3^2)] + \mathcal{O}(\epsilon), \end{aligned} \quad (\text{E.13})$$

$$\begin{aligned} I_{\frac{1}{2}+\epsilon\{\frac{3}{2}\frac{3}{2}\frac{3}{2}\}} &= \frac{1}{3} \left(\frac{\pi}{2}\right)^{3/2} \left[\frac{p_1^3 + p_2^3 + p_3^3}{\epsilon} - p_1 p_2 p_3 + (p_1^2 p_2 + p_2^2 p_1 + p_1^2 p_3 + p_3^2 p_1 + p_2^2 p_3 + p_3^2 p_2) \right. \\ &\quad \left. - (p_1^3 + p_2^3 + p_3^3) \ln(p_1 + p_2 + p_3) + \frac{4}{3}(p_1^3 + p_2^3 + p_3^3) \right]. \end{aligned} \quad (\text{E.14})$$

Notice that the previous formulas were obtained with the choice $u = 1$ and $v = 0$. Using the relations in Eq. (D.11) one can derive the integrals needed in our computation. For example

$$I_{\frac{7}{2}\{\frac{3}{2}\frac{3}{2}\frac{5}{2}\}} = \left(-p_3 \frac{\partial}{\partial p_3} I_{\frac{5}{2}+\epsilon\{\frac{3}{2}\frac{3}{2}\frac{3}{2}\}} + 2 \cdot \frac{3}{2} I_{\frac{5}{2}+\epsilon\{\frac{3}{2}\frac{3}{2}\frac{3}{2}\}} \right) \Big|_{\epsilon \rightarrow 0}, \quad (\text{E.15})$$

$$I_{\frac{7}{2}\{\frac{5}{2}\frac{5}{2}\frac{5}{2}\}} = \prod_{i=1}^3 \left(-p_i \frac{\partial}{\partial p_i} + 3 \right) I_{\frac{1}{2}+\epsilon\{\frac{3}{2}\frac{3}{2}\frac{3}{2}\}} \Big|_{\epsilon \rightarrow 0}. \quad (\text{E.16})$$

Notice that the integral in Eq. (E.16), by having $\alpha = 7/2$ and $\beta_i = 5/2$, does not satisfy the condition in Eq. (E.4), thus no pole in ϵ is present and the analytically continued result is finite.

F Polarisation structures in the X and P basis

In the following we provide the explicit formula for the structures \mathcal{E} that appear in the shape of the graviton three-point function, see Eq. (5.4). Here we choose the X and P basis. Assuming the external momenta \vec{p}_i , satisfying the momentum conservation, lying in the (x, y) -plane of a suitable reference frame, with \vec{p}_1 parallel to \hat{x} , one can define the polarisation tensors as

$$\epsilon_{ij}^P(\varphi_i) = \frac{1}{\sqrt{2}} \begin{pmatrix} -\sin^2 \varphi_i & \cos \varphi_i \sin \varphi_i & 0 \\ \cos \varphi_i \sin \varphi_i & -\cos^2 \varphi_i & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad (\text{F.1})$$

$$\epsilon_{ij}^X(\varphi_i) = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 0 & \sin \varphi_i \\ 0 & 0 & -\cos \varphi_i \\ \sin \varphi_i & -\cos \varphi_i & 0 \end{pmatrix}, \quad (\text{F.2})$$

where $\varphi_1 = 0$ and φ_2 and φ_3 identifies the angles between \vec{p}_1, \vec{p}_2 and \vec{p}_1, \vec{p}_3 , respectively. The expressions appearing in Eq. (5.4) in the $\{P, X\}$ basis are then given by

$$\begin{aligned} \mathcal{E}_1^P(\vec{p}_1|\vec{p}_2, \vec{p}_2) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{4\sqrt{2}p_1^2}, \\ \mathcal{E}_1^P(\vec{p}_2|\vec{p}_3, \vec{p}_3) &= \frac{(-p_1 + p_2 - p_3)(p_1 + p_2 - p_3)(-p_1 + p_2 + p_3)(p_1 + p_2 + p_3)}{4\sqrt{2}p_2^2}, \\ \mathcal{E}_1^P(\vec{p}_3|\vec{p}_1, \vec{p}_1) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{4\sqrt{2}p_3^2}, \end{aligned} \quad (\text{F.3})$$

$$\begin{aligned} \mathcal{E}_2^{PP}(\vec{p}_1, \vec{p}_2|\vec{p}_2, \vec{p}_3) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)(p_1^2 + p_2^2 - p_3^2)}{16p_1^2p_2^2}, \\ \mathcal{E}_2^{XX}(\vec{p}_1, \vec{p}_2|\vec{p}_2, \vec{p}_3) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{8p_1p_2}, \\ \mathcal{E}_2^{PP}(\vec{p}_2, \vec{p}_3|\vec{p}_3, \vec{p}_1) &= \frac{(-p_1 + p_2 - p_3)(p_1 + p_2 - p_3)(-p_1 + p_2 + p_3)(p_1 + p_2 + p_3)(-p_1^2 + p_2^2 + p_3^2)}{16p_2^2p_3^2}, \\ \mathcal{E}_2^{XX}(\vec{p}_2, \vec{p}_3|\vec{p}_3, \vec{p}_1) &= -\frac{(-p_1 + p_2 - p_3)(p_1 + p_2 - p_3)(-p_1 + p_2 + p_3)(p_1 + p_2 + p_3)}{8p_2p_3}, \\ \mathcal{E}_2^{PP}(\vec{p}_1, \vec{p}_3|\vec{p}_2, \vec{p}_1) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)(p_1^2 - p_2^2 + p_3^2)}{16p_1^2p_3^2}, \\ \mathcal{E}_2^{XX}(\vec{p}_1, \vec{p}_3|\vec{p}_2, \vec{p}_1) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{8p_1p_3}, \end{aligned} \quad (\text{F.4})$$

$$\begin{aligned} \mathcal{E}_4^{PPP}(\vec{p}_1, \vec{p}_2, \vec{p}_3|\vec{p}_4, \vec{p}_5) &= \frac{-(p_1^2 - p_2^2)^4 + 2(p_1^2 - p_2^2)^2(p_1^2 + p_2^2)p_3^2 - 2(p_1^2 + p_2^2)p_3^6 + p_3^8}{32\sqrt{2}p_1^2p_2^2p_3^2}, \\ \mathcal{E}_4^{XXP}(\vec{p}_1, \vec{p}_2, \vec{p}_3|\vec{p}_4, \vec{p}_5) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{8\sqrt{2}p_1p_2}, \\ \mathcal{E}_4^{XPX}(\vec{p}_1, \vec{p}_2, \vec{p}_3|\vec{p}_4, \vec{p}_5) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)(p_1^2 - p_2^2 - p_3^2)}{16\sqrt{2}p_1p_2^2p_3}, \\ \mathcal{E}_4^{PXX}(\vec{p}_1, \vec{p}_2, \vec{p}_3|\vec{p}_4, \vec{p}_5) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)(p_1^2 - p_2^2 + p_3^2)}{16\sqrt{2}p_1^2p_2p_3}, \end{aligned}$$

$$\begin{aligned}
\mathcal{E}_4^{PPP}(\vec{p}_3, \vec{p}_2, \vec{p}_1 | \vec{p}_1, \vec{p}_3) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{32\sqrt{2}p_1^2p_2^2p_3^2} \\
&\quad \times (p_1^2 + p_2^2 - p_3^2)(p_1^2 - p_2^2 + p_3^2), \\
\mathcal{E}_4^{XXP}(\vec{p}_3, \vec{p}_2, \vec{p}_1 | \vec{p}_1, \vec{p}_3) &= -\frac{(-p_1 + p_2 - p_3)(p_1 + p_2 - p_3)(-p_1 + p_2 + p_3)(p_1 + p_2 + p_3)}{8\sqrt{2}p_2p_3}, \\
\mathcal{E}_4^{XPX}(\vec{p}_3, \vec{p}_2, \vec{p}_1 | \vec{p}_1, \vec{p}_3) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)(p_1^2 + p_2^2 - p_3^2)}{16\sqrt{2}p_1p_2^2p_3}, \\
\mathcal{E}_4^{PXX}(\vec{p}_3, \vec{p}_2, \vec{p}_1 | \vec{p}_1, \vec{p}_3) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)(p_1^2 - p_2^2 + p_3^2)}{16\sqrt{2}p_1p_2p_3^2}, \\
\mathcal{E}_4^{PPP}(\vec{p}_1, \vec{p}_3, \vec{p}_2 | \vec{p}_2, \vec{p}_1) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)(p_1^2 - p_2^2 - p_3^2)}{32\sqrt{2}p_1^2p_2^2p_3^2} \\
&\quad \times (p_1^2 + p_2^2 - p_3^2), \\
\mathcal{E}_4^{XXP}(\vec{p}_1, \vec{p}_3, \vec{p}_2 | \vec{p}_2, \vec{p}_1) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{8\sqrt{2}p_1p_3}, \\
\mathcal{E}_4^{XPX}(\vec{p}_1, \vec{p}_3, \vec{p}_2 | \vec{p}_2, \vec{p}_1) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)(p_1^2 - p_2^2 - p_3^2)}{16\sqrt{2}p_1p_2p_3^2}, \\
\mathcal{E}_4^{PXX}(\vec{p}_1, \vec{p}_3, \vec{p}_2 | \vec{p}_2, \vec{p}_1) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{16\sqrt{2}p_1^2p_2p_3} \\
&\quad \times (p_1^2 + p_2^2 - p_3^2), \tag{F.5}
\end{aligned}$$

$$\begin{aligned}
\mathcal{E}_3^{PP}(\vec{p}_1, \vec{p}_2) &= \frac{1}{8} \left(4 + \frac{(p_1^2 + p_2^2 - p_3^2)^2}{p_1^2p_2^2} \right), \\
\mathcal{E}_3^{XX}(\vec{p}_1, \vec{p}_2) &= -\frac{p_1^2 + p_2^2 - p_3^2}{2p_1p_2}, \\
\mathcal{E}_3^{PP}(\vec{p}_2, \vec{p}_3) &= \frac{p_1^4 + p_2^4 + 6p_2^2p_3^2 + p_3^4 - 2p_1^2(p_2^2 + p_3^2)}{8p_2^2p_3^2}, \\
\mathcal{E}_3^{XX}(\vec{p}_2, \vec{p}_3) &= -\frac{-p_1^2 + p_2^2 + p_3^2}{2p_2p_3}, \\
\mathcal{E}_3^{PP}(\vec{p}_1, \vec{p}_3) &= \frac{1}{8} \left(4 + \frac{(p_1^2 - p_2^2 + p_3^2)^2}{p_1^2p_3^2} \right), \\
\mathcal{E}_3^{XX}(\vec{p}_1, \vec{p}_3) &= -\frac{p_1^2 - p_2^2 + p_3^2}{2p_1p_3}, \tag{F.6}
\end{aligned}$$

$$\begin{aligned}
\mathcal{E}_5^{PPP}(\vec{p}_1, \vec{p}_2, \vec{p}_3) &= -\frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)(p_1^2 + p_2^2 + p_3^2)}{16\sqrt{2}p_1^2p_2^2p_3^2}, \\
\mathcal{E}_5^{XXP}(\vec{p}_1, \vec{p}_2, \vec{p}_3) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{8\sqrt{2}p_1p_2p_3^2}, \\
\mathcal{E}_5^{XPX}(\vec{p}_1, \vec{p}_2, \vec{p}_3) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{8\sqrt{2}p_1p_2^2p_3}, \\
\mathcal{E}_5^{PXX}(\vec{p}_1, \vec{p}_2, \vec{p}_3) &= \frac{(p_1 - p_2 - p_3)(p_1 + p_2 - p_3)(p_1 - p_2 + p_3)(p_1 + p_2 + p_3)}{8\sqrt{2}p_1^2p_2p_3}, \tag{F.7}
\end{aligned}$$

and the other combinations are vanishing.

G Polarisation structures in the chiral basis

In this Appendix we provide the explicit formula for the structures \mathcal{E} in Eq. (5.4) in the chiral basis. With respect to the X and P basis one has

$$\epsilon_{ij}^R = \frac{\epsilon_{ij}^P + i\epsilon_{ij}^X}{\sqrt{2}} \quad \text{and} \quad \epsilon_{ij}^L = \frac{\epsilon_{ij}^P - i\epsilon_{ij}^X}{\sqrt{2}}. \quad (\text{G.1})$$

We can express the structures \mathcal{E} as a function of the ratios between the external momenta, i.e $r_2 = \frac{p_2}{p_1}$ and $r_3 = \frac{p_3}{p_1}$, and for generic polarisation $\lambda_1, \lambda_2, \lambda_3$ of the chiral basis, that is $\lambda = \{R, L\}$. From the explicit formula provided in the previous appendix, one can write the polarisation tensors in the new basis as

$$\epsilon_{ij}^\lambda(\varphi_i) = \frac{1}{2} \begin{pmatrix} -\sin^2 \varphi_i & \cos \varphi_i \sin \varphi_i & i\lambda \sin \varphi_i \\ \cos \varphi_i \sin \varphi_i & -\cos^2 \varphi_i & -i\lambda \cos \varphi_i \\ i\lambda \sin \varphi_i & -i\lambda \cos \varphi_i & 1 \end{pmatrix}, \quad (\text{G.2})$$

where again $\varphi_1 = 0$ and φ_2 and φ_3 identifies the angles between \vec{p}_1, \vec{p}_2 and \vec{p}_1, \vec{p}_3 , respectively. The R polarisation corresponds to $\lambda = 1$ while the L polarisation corresponds to $\lambda = -1$. One can check that this construction satisfies the normalisation condition in Eq. (2.8) and it is also transverse and traceless. The expressions appearing in Eq. (5.4) in the $\{R, L\}$ basis are

$$\begin{aligned} \mathcal{E}_1^{\lambda_1}(\vec{p}_1|\vec{p}_2, \vec{p}_2) &= \frac{p_1^2}{8} [r_2^4 + (-1 + r_3^2)^2 - 2r_2^2(1 + r_3^2)], \\ \mathcal{E}_1^{\lambda_1}(\vec{p}_2|\vec{p}_3, \vec{p}_3) &= \frac{p_1^2}{8r_2^2} [r_2^4 + (-1 + r_3^2)^2 - 2r_2^2(1 + r_3^2)], \\ \mathcal{E}_1^{\lambda_1}(\vec{p}_3|\vec{p}_1, \vec{p}_1) &= \frac{p_1^2}{8r_3^2} [r_2^4 + (-1 + r_3^2)^2 - 2r_2^2(1 + r_3^2)], \end{aligned} \quad (\text{G.3})$$

$$\begin{aligned} \mathcal{E}_2^{\lambda_1\lambda_2}(\vec{p}_1, \vec{p}_2|\vec{p}_2, \vec{p}_3) &= \frac{p_1^2}{32r_2^2} [r_2^4 + (-1 + r_3^2)^2 - 2r_2^2(1 + r_3^2)] [1 + r_2^2 - r_3^2 + 2r_2\lambda_1\lambda_2], \\ \mathcal{E}_2^{\lambda_2\lambda_3}(\vec{p}_2, \vec{p}_3|\vec{p}_3, \vec{p}_1) &= \frac{p_1^2}{32r_2^2r_3^2} [r_2^4 + (-1 + r_3^2)^2 - 2r_2^2(1 + r_3^2)] [-1 + r_2^2 + r_3^2 + 2r_2r_3\lambda_2\lambda_3], \\ \mathcal{E}_2^{\lambda_1\lambda_3}(\vec{p}_1, \vec{p}_3|\vec{p}_2, \vec{p}_1) &= \frac{p_1^2}{32r_3^2} [r_2^4 + (-1 + r_3^2)^2 - 2r_2^2(1 + r_3^2)] [1 - r_2^2 + r_3^2 + 2r_3\lambda_1\lambda_3], \end{aligned} \quad (\text{G.4})$$

$$\begin{aligned} \mathcal{E}_3^{\lambda_1\lambda_2}(\vec{p}_1, \vec{p}_2) &= \frac{r_2^4 - 2r_2^2(-3 + r_3^2) + (-1 + r_3^2)^2 + 4r_2^3\lambda_1\lambda_2 - 4r_2(-1 + r_3^2)\lambda_1\lambda_2}{16r_2^2}, \\ \mathcal{E}_3^{\lambda_2\lambda_3}(\vec{p}_2, \vec{p}_3) &= \frac{1 - 2r_2^2 + r_2^4 - 2r_3^2 + 6r_2^2r_3^2 + r_3^4 + 4r_2r_3(-1 + r_2^2 + r_3^2)\lambda_2\lambda_3}{16r_2^2r_3^2}, \\ \mathcal{E}_3^{\lambda_1\lambda_3}(\vec{p}_1, \vec{p}_3) &= \frac{1 + r_2^4 + 6r_3^2 + r_3^4 + 4(r_3 + r_3^3)\lambda_1\lambda_3 - 2r_2^2(1 + r_3^2 + 2r_3\lambda_1\lambda_3)}{16r_3^2}, \end{aligned} \quad (\text{G.5})$$

$$\begin{aligned} \mathcal{E}_4^{\lambda_1\lambda_2\lambda_3}(\vec{p}_1, \vec{p}_2, \vec{p}_3|\vec{p}_4, \vec{p}_5) &= -\frac{p_1^2}{128r_2^2r_3^2} [(-1 + r_2^2)^2 - 2(1 + r_2^2)r_3^2 + r_3^4] \\ &\times [1 - 2r_2^2 + r_2^4 - r_3^4 - 4r_2r_3^2\lambda_1\lambda_2 - 2r_3((-1 + r_2^2 + r_3^2)\lambda_1 + r_2(1 - r_2^2 + r_3^2)\lambda_2)\lambda_3], \\ \mathcal{E}_4^{\lambda_3\lambda_2\lambda_1}(\vec{p}_3, \vec{p}_2, \vec{p}_1|\vec{p}_1, \vec{p}_3) &= -\frac{p_1^2}{128r_2r_3^2} [(-1 + r_2^2)^2 - 2(1 + r_2^2)r_3^2 + r_3^4] \\ &\times [(-1 + r_2^2 - r_3^2)(1 + r_2^2 - r_3^2 + 2r_2\lambda_1\lambda_2) - 2r_3((1 + r_2^2 - r_3^2)\lambda_1 + 2r_2\lambda_2)\lambda_3], \\ \mathcal{E}_4^{\lambda_1\lambda_3\lambda_2}(\vec{p}_1, \vec{p}_3, \vec{p}_2|\vec{p}_2, \vec{p}_1) &= \frac{p_1^2}{128r_2^2r_3^2} [(-1 + r_2^2)^2 - 2(1 + r_2^2)r_3^2 + r_3^4] \\ &\times [(-1 + r_2^2 + r_3^2)(1 + r_2^2 - r_3^2 + 2r_2\lambda_1\lambda_2) + 2r_2r_3(2r_2\lambda_1 + \lambda_2 + r_2^2\lambda_2 - r_3^2\lambda_2)\lambda_3], \end{aligned} \quad (\text{G.6})$$

$$\begin{aligned}\mathcal{E}_5^{\lambda_1\lambda_2\lambda_3}(\vec{p}_1, \vec{p}_2, \vec{p}_3) = & -\frac{1}{64r_2^2r_3^2} [2r_2 + (1 + r_2^2 - r_3^2)\lambda_1\lambda_2] [-2r_3 + (-1 + r_2^2 - r_3^2)\lambda_1\lambda_3] \\ & \times [2r_2r_3 + (-1 + r_2^2 + r_3^2)\lambda_2\lambda_3].\end{aligned}\tag{G.7}$$

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